



Optimal Error Estimates of a Time-Spectral Method for Fractional Diffusion Problems with Low Regularity Data

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Abstract

This paper is devoted to the error analysis of a time-spectral algorithm for fractional diffusion problems of order α ($0 < \alpha < 1$). The solution regularity in the Sobolev space is revisited and new regularity results in the Besov space are established. A time-spectral algorithm is developed which adopts a standard spectral method and a conforming linear finite element method for temporal and spatial discretizations, respectively. Optimal error estimates are derived with nonsmooth data. Particularly, a sharp temporal convergence rate $1 + 2\alpha$ is shown theoretically and numerically.

Keywords Fractional diffusion problem · Finite element method · Spectral method · Jacobi polynomial · Low regularity · Besov space · Optimal error estimate

1 Introduction

Let $T > 0$ be a finite time. This paper considers the following time fractional diffusion equation:

$$\begin{cases} D_{0+}^{\alpha}(u - u_0) - \Delta u = f & \text{in } \Omega \times (0, T), \\ u = 0 & \text{on } \partial\Omega \times (0, T), \\ u(0) = u_0 & \text{in } \Omega, \end{cases} \quad (1)$$

where u_0, f are known data, $\Omega \subset \mathbb{R}^d$ ($d = 1, 2, 3$) is a convex polygonal domain and D_{0+}^{α} is a Riemann–Liouville fractional differential operator with order $\alpha \in (0, 1)$; see Sect. 2.

The problem (1) is widely used in modeling of anomalous diffusion process [45, 46] and anomalous transport [38, 65], for its capability of accurately describing models with non-

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locality and historical memory [23,52]. For theoretical study to the problem, e.g. the weak solution and its regularity, we refer to [16,33,35,54].

Many numerical methods have been developed in the past a dozen years. Among existing works, three types of temporal discretization are most prevailing, i.e., the finite difference method (L-type schemes [2,24,36,41] and convolution quadrature methods [12,14,62,64]), the finite element method [25,27,29,30] and the spectral method [26,35,55,66]. Under certain circumstances, problem (1) has an equivalent form

$$\begin{cases} u_t - D_{0+}^{1-\alpha} \Delta u = g & \text{in } \Omega \times (0, T), \\ u = 0 & \text{on } \partial\Omega \times (0, T), \\ u(0) = u_0 & \text{in } \Omega, \end{cases} \quad (2)$$

where $g = D_{0+}^{1-\alpha} f$. In the literature, both (1) and (2) are called time fractional diffusion equations or time fractional subdiffusion equations. For the solution regularity and numerical analysis of problem (2), especially in the case of nonsmooth data, we refer the reader to [28,42,43,48,50,51].

It is well-known that the solution to problem (1) generally has boundary singularity (near $0+$) in temporal direction. If $f = 0$ and u_0 is (or not) smooth, or $u_0 = 0$ and f is smooth, then one can obtain growth estimates of the solution [19,20] or even find out the leading singular term t^α of the solution [33]. Due to the singularity, the accuracy $2 - \alpha$ of the L1 scheme [36] deteriorates into 1 in the case of $f = 0$ and $u_0 \neq 0$, whether the initial data u_0 is smooth or not [21]. In the same situation, a piecewise constant discontinuous Galerkin (DG) semidiscretization was analyzed in [44]. Let us summarize the error estimate results of [21,44] as follows: for any temporal grid node $t_j = j\tau$ with $j = 1, 2, \dots, J$ and $\tau = T/J$,

$$\|(u - U)(t_j)\|_{L^2(\Omega)} \leq C \begin{cases} t_j^{\alpha-1} \tau \|u_0\|_{\dot{H}^2(\Omega)}, & \text{for L1 in [22]} \\ t_j^{-1} \tau \|u_0\|_{L^2(\Omega)}, & \text{for L1 in [22] and DG in [45].} \end{cases} \quad (3)$$

Hence, if $u_0 \in L^2(\Omega)$, then the first order accuracy under $L^\infty(0, T; L^2(\Omega))$ -norm is only achieved far away from the origin, and the global convergence rate degenerates as t_j approaches to zero; and if $u_0 \in \dot{H}^2(\Omega)$, then the global rate reduces to τ^α . These error estimates in (3) coincide with the solution regularity in Sobolev space (see Theorem 3.1):

$$\begin{cases} \epsilon^{3/2} \|u\|_{H^{1/2-\epsilon}(0, T; L^2(\Omega))} \leq C_{\alpha, T} \|u_0\|_{L^2(\Omega)}, & 0 < \epsilon \leq 1/2, \\ \sqrt{2\gamma - \gamma^2} \|u\|_{H^{(1+\alpha\gamma)/2}(0, T; L^2(\Omega))} \leq C_{\alpha, T, \Omega} \|u_0\|_{\dot{H}^\gamma(\Omega)}, & 0 < \gamma < 2. \end{cases}$$

To improve the temporal accuracy, graded meshes were used in [24,49,58] and some correction techniques were proposed in [13,22,31,63]. However, most of the existing works using graded meshes require some assumption of growth estimate on the true solution, and the analysis of correction schemes for (3) are mainly based on the Laplace transform, which is only applicable for uniform temporal grids, and the obtained convergence rates have the form $t_j^{-q} \tau^p$ with $0 < q \leq p$ (like (3)), which deteriorates near the origin. In [32], several technical stability results were developed to establish the optimal first order accuracy of a piecewise constant DG method on graded meshes. Also, spectral methods with singular basis functions were presented [7,55] but so far no rigorous convergence analysis is available with low regularity data. In [9], a multi-domain Petrov–Galerkin spectral method with a singular basis and geometrically graded meshes was proposed, and the exponential decay was verified numerically with nonsmooth initial data. We are also aware of the recent work [8], where an

exponentially convergent rational approximation scheme has been proposed for the spatial semi-discretization of (1).

In the 1980s, Gui and Babuška [18] established the optimal approximation order $1 + 2\beta$ under the L^2 -norm of the Legendre orthogonal expansion for the singular function $(x + 1)^\beta$ on $(-1, 1)$. Later Babuška and Suri [4] extended this to a p -version finite element method for solving two dimensional elliptic equations, and proved the sharp rate 2β under the energy norm, by assuming that the solution has the explicit singular expression r^β around the origin. Note that these functions have boundary singularities as well but the achieved convergence rates agree with their regularity in the Besov space.

In view of the boundary singularity of the solution to problem (1), one may wonder whether this happens to the convergence behavior of a time-spectral method. For simplicity, let us start with a fractional ordinary differential equation

$$D_{0+}^\alpha (y - y_0) + \lambda y = 0 \quad \text{in } (0, T], \quad (4)$$

where $y_0 \in \mathbb{R}$ and $\lambda > 0$. Invoking the Laplace transform gives the solution expression

$$y(t) = y_0 \sum_{k=0}^{\infty} \frac{(-\lambda t^\alpha)^k}{\Gamma(\alpha k + 1)}, \quad 0 \leq t \leq T. \quad (5)$$

Note that for a given fixed (small) $\lambda > 0$, we have $y \in H^{1/2+\alpha-\epsilon}(0, T)$ for any $\epsilon > 0$ (see Remark 3.1). We adopt a standard Legendre spectral method with polynomial degree $M \in \mathbb{N}$ to seek an approximation Y_M and use Y_{100} as a reference solution. Figure 1 plots the convergence order $1 + 2\alpha$ under L^2 -norm in the case that $\lambda = y_0 = T = 1$. This agrees with the Besov regularity of (5): $\mathbb{B}_{-\alpha,0}^{1+2\alpha-\epsilon}(0, T)$ for any $\epsilon > 0$; see Lemma 3.4. However, if λ is extremely large or goes to infinity, then we see from Lemma 4.1 that the convergence rate will be ruined (we also refer the reader to [9, Section 1.2] for detailed numerical investigations in this case).

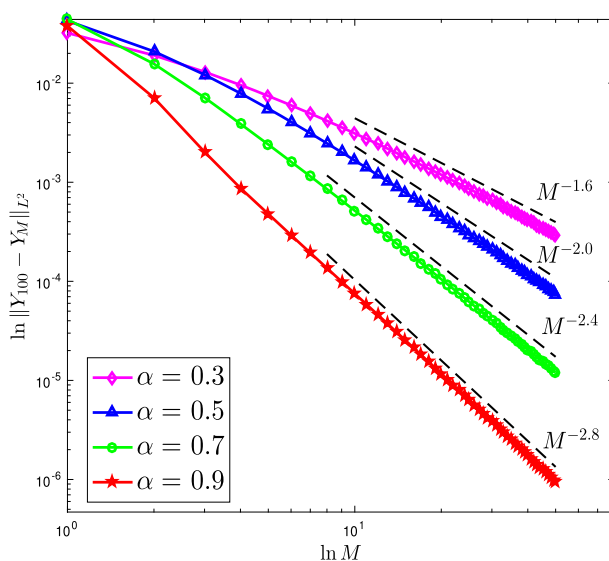


Fig. 1 Discretization errors of (4) with $\lambda = y_0 = T = 1$. The predicted accuracy is $M^{-1-2\alpha}$

As for the model problem (1) itself, although there exists a space-time spectral method that has been proposed in [35], to our best knowledge, no such rate $1 + 2\alpha$ has been mentioned numerically and established rigorously. It is nontrivial to obtain this since now the impact of large λ comes from the negative Laplacian operator $-\Delta$ (or its discrete version $-\Delta_h$). This motivates us to revisit the convergence analysis of the time-spectral method for time fractional diffusion problem (1). Can we prove the optimal approximation order in terms of Besov regularity with nonsmooth data? Especially, whether the accuracy $1 + 2\alpha$ can be established or improved?

In this work, we give partially positive answers to these questions mentioned above. Optimal error estimates with respect to the solution regularity in Besov space are established with low regularity data. Moreover, temporal convergence rates $1 + \alpha$ and $1 + 2\alpha$ under $H^{\alpha/2}(0, T; L^2(\Omega))$ -norm and $L^2(0, T; \dot{H}^1(\Omega))$ -norm are derived, respectively, which are sharp and cannot be improved even for smoother data.

The rest of this paper is organized as follows. In Sect. 2, we introduce some notations, including standard conventions, functional spaces and fractional calculus operators. Then in Sect. 3, we define the weak solution and establish its regularity results in Sobolev space and Besov space, and we present our main error estimates in Sect. 4. Finally, we conduct several numerical experiments in Sect. 5 and give some concluding remarks in Sect. 6.

2 Preliminary

For ease of notation, we make some standard conventions. For a Lebesgue measurable subset ω of \mathbb{R}^l ($l = 1, 2, 3$), we use $H^\gamma(\omega)$ ($\gamma \in \mathbb{R}$) and $H_0^\gamma(\omega)$ ($\gamma > 0$) to denote two standard Sobolev spaces [59]. Given $1 \leq p < \infty$, if ω is an interval and μ is a nonnegative measurable function on ω , then $L_\mu^p(\omega)$ denotes the weighted L^p -space, and the symbol $\langle a, b \rangle_\mu$ means $\int_\omega ab \mu$ whenever $ab \in L_\mu^1(\omega)$; if ω is a Lebesgue measurable set of \mathbb{R}^l ($l = 1, 2, 3, 4$), then $\langle a, b \rangle_\omega$ stands for $\int_\omega ab$ whenever $ab \in L^1(\omega)$; if X is a Banach space, then $\langle \cdot, \cdot \rangle_X$ means the duality pairing between X^* (the dual space of X) and X . In particular, if X is a Hilbert space, then $\langle \cdot, \cdot \rangle_X$ means its inner product. If X and Y are two Banach spaces, then $[X, Y]_{\theta, 2}$ is the interpolation space constructed by the well-known K -method [5]. For $k \in \mathbb{N}$ and any d -polytope $\omega \subset \mathbb{R}^d$ ($d = 1, 2, 3$), $P_k(\omega)$ denotes the set of all polynomials defined on ω with degree no more than k .

As we all know, $L^2(\Omega)$ has an orthonormal basis $\{\phi_n\}_{n=0}^\infty$ such that [11]

$$\begin{cases} -\Delta \phi_n = \lambda_n \phi_n, & \text{in } \Omega, \\ \phi_n = 0, & \text{on } \partial\Omega, \end{cases}$$

where $\{\lambda_n\}_{n=0}^\infty$ is a nondecreasing real positive sequence and $\lambda_0 = \|\nabla \phi_0\|_{L^2(\Omega)}^2 > 0$ depends only on Ω . For any $\gamma \in \mathbb{R}$, define

$$\dot{H}^\gamma(\Omega) := \left\{ \sum_{n=0}^\infty c_n \phi_n : \sum_{n=0}^\infty \lambda_n^\gamma c_n^2 < \infty \right\}$$

and equip this space with the inner product

$$\left(\sum_{n=0}^\infty c_n \phi_n, \sum_{n=0}^\infty d_n \phi_n \right)_{\dot{H}^\gamma(\Omega)} := \sum_{n=0}^\infty \lambda_n^\gamma c_n d_n, \quad \text{for all } \sum_{n=0}^\infty c_n \phi_n, \sum_{n=0}^\infty d_n \phi_n \in \dot{H}^\gamma(\Omega).$$

The induced norm is denoted by $\|\cdot\|_{\dot{H}^\gamma(\Omega)} = \sqrt{(\cdot, \cdot)_{\dot{H}^\gamma(\Omega)}}$. Note that $\dot{H}^\gamma(\Omega)$ is a Hilbert space and has an orthonormal basis $\{\lambda_n^{-\gamma/2} \phi_n\}_{n=0}^\infty$.

Let ${}_0H^2(0, T) := \{v \in H^2(0, T) : v(0) = v'(0) = 0\}$ and equip this space with the norm $\|v\|_{{}_0H^2(0, T)} := \|v''\|_{L^2(0, T)}$. Given any $0 < \gamma < 2$, we introduce the space

$${}_0H^\gamma(0, T) := [L^2(0, T), {}_0H^2(0, T)]_{\gamma/2, 2}.$$

Applying the interpolation theorem of bounded linear operators [39, Theorem 1.6] yields

$$\|v\|_{[L^2(0, T), H^2(0, T)]_{\gamma/2, 2}} \leq \|v\|_{{}_0H^\gamma(0, T)} \quad \forall v \in {}_0H^\gamma(0, T). \quad (6)$$

In addition, if $0 < \gamma < 1/2$, then by [37, Chapter 1], the relation ${}_0H^\gamma(0, T) = H^\gamma(0, T)$ holds in the sense of equivalent norms, and in this case (i.e., $0 < \gamma < 1/2$) we have an alternative norm, which is defined by

$$|w|_{H^\gamma(0, T)} := \left(\int_{\mathbb{R}} |\xi|^{2\gamma} |\mathcal{F}(w\chi_{(0, T)})(\xi)|^2 d\xi \right)^{1/2} \quad \forall w \in H^\gamma(0, T),$$

where $\mathcal{F} : L^2(\mathbb{R}) \rightarrow L^2(\mathbb{R})$ is the Fourier transform and $\chi_{(0, T)}$ denotes the indicator function of $(0, T)$.

Let X be a separable Hilbert space with an inner product $(\cdot, \cdot)_X$ and an orthonormal basis $\{e_n : n \in \mathbb{N}\}$. For any $\gamma \in \mathbb{R}$, let $H^\gamma(0, T; X)$ be a usual vector-valued Sobolev space defined by (cf. [37, Section 1.3])

$$H^\gamma(0, T; X) := \left\{ \sum_{n=0}^\infty v_n e_n : \sum_{n=0}^\infty \|v_n\|_{H^\gamma(0, T)}^2 < \infty \right\}, \quad (7)$$

with the norm

$$\|v\|_{H^\gamma(0, T; X)} := \left(\sum_{n=0}^\infty \|(v, e_n)_X\|_{H^\gamma(0, T)}^2 \right)^{1/2} \quad \forall v \in H^\gamma(0, T; X).$$

The spaces $L^2_{\mu^{a,b}}(0, T; X)$ and ${}_0H^\gamma(0, T; X)$ for $0 < \gamma < 2$ can be defined similarly as (7).

For $a, b > -1$, let $\{S_k^{a,b}\}_{k=0}^\infty$ be the family of shifted Jacobi polynomials on $(0, T)$ with respect to the weight $\mu^{a,b}(t) = (T-t)^a t^b$; see ‘‘Appendix A’’. Given $\gamma \geq 0$, we introduce the Besov space (also known as the weighted Sobolev space, cf. [3]) defined by

$$\mathbb{B}_{a,b}^\gamma(0, T) := \left\{ \sum_{k=0}^\infty v_k S_k^{a,b} : \sum_{k=0}^\infty (1 + k^{2\gamma}) \xi_k^{a,b} v_k^2 < \infty \right\}, \quad (8)$$

where $\xi_k^{a,b}$ is given by (80), and endow this space with the norm

$$\|v\|_{\mathbb{B}_{a,b}^\gamma(0, T)} := \left(\sum_{k=0}^\infty (1 + k^{2\gamma}) \xi_k^{a,b} v_k^2 \right)^{1/2} \quad \forall v = \sum_{k=0}^\infty v_k S_k^{a,b} \in \mathbb{B}_{a,b}^\gamma(0, T).$$

In addition, for any separable Hilbert space X , the vector-valued space $\mathbb{B}_{a,b}^\gamma(0, T; X)$ can be defined in a similar way as that of (7).

To the end, let us introduce the Riemann–Liouville fractional calculus operators and list some important lemmas. For any $\gamma > 0$ and $v \in L^1(0, T; X)$, define the fractional integrals

of order γ as follows:

$$\begin{aligned} (D_{0+}^{-\gamma} v)(t) &:= \frac{1}{\Gamma(\gamma)} \int_0^t (t-s)^{\gamma-1} v(s) \, ds, \quad t \in (0, T), \\ (D_{T-}^{-\gamma} v)(t) &:= \frac{1}{\Gamma(\gamma)} \int_t^T (s-t)^{\gamma-1} v(s) \, ds, \quad t \in (0, T), \end{aligned}$$

where $\Gamma(\cdot)$ denotes the Gamma function $\Gamma(z) := \int_0^\infty t^{z-1} e^{-t} \, dt$ for $z > 0$. For $k-1 < \gamma < k$ with positive integer $k \in \mathbb{N}_+$, define the left-sided and right-sided Riemann–Liouville fractional derivative operators of order γ respectively by

$$D_{0+}^\gamma := D^k D_{0+}^{\gamma-k}, \quad D_{T-}^\gamma := (-D)^k D_{T-}^{\gamma-k},$$

where D is the first-order generalized derivative operator.

Lemma 2.1 [10] *If $-1/2 < \gamma < 1/2$ and $v, w \in H^{\max\{0, \gamma\}}(0, T)$, then*

$$\begin{aligned} \langle D_{0+}^\gamma v, D_{T-}^\gamma v \rangle_{(0, T)} &= \cos(\gamma\pi) |v|_{H^\gamma(0, T)}^2, \\ \cos(\gamma\pi) \|D_{0+}^\gamma v\|_{L^2(0, T)}^2 &\leq \langle D_{0+}^\gamma v, D_{T-}^\gamma v \rangle_{(0, T)} \leq \sec(\gamma\pi) \|D_{0+}^\gamma v\|_{L^2(0, T)}^2, \\ \langle D_{0+}^{2\gamma} v, w \rangle_{H^\gamma(0, T)} &= \langle D_{0+}^\gamma v, D_{T-}^\gamma w \rangle_{(0, T)} \leq |v|_{H^\gamma(0, T)} |w|_{H^\gamma(0, T)}. \end{aligned}$$

Lemma 2.2 [40] *If $v \in {}_0H^\gamma(0, T)$ with $0 < \gamma < 2$, then*

$$C_1 \|D_{0+}^\gamma v\|_{L^2(0, T)} \leq \|v\|_{{}_0H^\gamma(0, T)} \leq C_2 \|D_{0+}^\gamma v\|_{L^2(0, T)},$$

where C_1 and C_2 depend only on γ .

3 Weak Solution and Regularity

This section is to revisit the solution regularity of problem (1) in terms of proper Sobolev spaces and establish new regularity results in Besov spaces.

Following [27, 35], we first introduce the weak solution to problem (1). To do so, set

$$\mathcal{X} := H^{\alpha/2}(0, T; L^2(\Omega)) \cap L^2(0, T; \dot{H}^1(\Omega)), \quad (9)$$

and endow this space with the norm

$$\|\cdot\|_{\mathcal{X}} := \left(|\cdot|_{H^{\alpha/2}(0, T; L^2(\Omega))}^2 + \|\cdot\|_{L^2(0, T; \dot{H}^1(\Omega))}^2 \right)^{1/2}.$$

Assuming that $f + D_{0+}^\alpha u_0 \in \mathcal{X}^*$, we call $u \in \mathcal{X}$ a weak solution to problem (1) if

$$\langle D_{0+}^\alpha u, v \rangle_{H^{\alpha/2}(0, T; L^2(\Omega))} + \langle \nabla u, \nabla v \rangle_{L^2(0, T; L^2(\Omega))} = \langle f + D_{0+}^\alpha u_0, v \rangle_{\mathcal{X}} \quad \forall v \in \mathcal{X}. \quad (10)$$

As mentioned in [27, Remark 2.2], the well-posedness of the weak formulation (10) follows from the Lax–Milgram theorem and Lemma 2.1. More precisely, if $f + D_{0+}^\alpha u_0 \in \mathcal{X}^*$, then problem (1) admits a unique weak solution in the sense of (10) such that

$$\|u\|_{\mathcal{X}} \leq C_\alpha \|f + D_{0+}^\alpha u_0\|_{\mathcal{X}^*}.$$

In the sequel, set $\gamma_0 := \min\{2, 1/\alpha\}$. To establish more elaborate regularity estimates, we apply the Galerkin method that reduces (10) to a family of ordinary differential equations, to which the solutions can be used to recover the weak solution to (10) through a series expression; see the lemma below.

Proposition 3.1 Assume $f \in L^2(0, T; \dot{H}^{-1}(\Omega))$ and $u_0 \in \dot{H}^\gamma(\Omega)$ where $\gamma > 1 - \gamma_0$. The solution to (10) is given by $u = \sum_{n=0}^{\infty} y_n \phi_n$, where $y_n \in H^{\alpha/2}(0, T)$ satisfies

$$\langle D_{0+}^\alpha (y_n - y_{n,0}), z \rangle_{H^{\alpha/2}(0,T)} + \lambda_n \langle y_n, z \rangle_{(0,T)} = \langle f_n, z \rangle_{(0,T)}, \quad (11)$$

for all $z \in H^{\alpha/2}(0, T)$, where $y_{n,0} = \langle u_0, \phi_n \rangle_{\dot{H}^\gamma(\Omega)}$ and $f_n = \langle f, \phi_n \rangle_{\dot{H}^1(\Omega)}$.

Proof The proof here is actually in line with that of [27, Theorem 3.1], where the case $0 < \alpha < 1/2$ has been considered. The case of $1/2 \leq \alpha < 1$ follows similarly. \square

3.1 Regularity in Sobolev Space

We now revisit the Sobolev regularity of the solution to (10). Thanks to Proposition 3.1, this can be done by investigating problem (11), which, in a general form, is equivalent to

$$D_{0+}^\alpha (y - y_0) + \lambda y = g, \quad (12)$$

where $\lambda > 0$, $y_0 \in \mathbb{R}$ and $g \in L^2(0, T)$. Indeed, in [27, Lemmas 3.1–3.3] we have established corresponding regularity results via variational approach, and Sobolev regularities of the weak solution have been given in [27, Theorems 3.1–3.3].

For the case $u_0 = 0$, if $f \in L^2(0, T; \dot{H}^\gamma(\Omega))$ with $-1 \leq \gamma \leq 1$, then

$$\|u\|_{0H^{\alpha(1+\gamma/2)}(0,T;L^2(\Omega))} + \|u\|_{L^2(0,T;\dot{H}^{2+\gamma}(\Omega))} \leq C_{\alpha,T} \|f\|_{L^2(0,T;\dot{H}^\gamma(\Omega))}, \quad (13)$$

and based on the proof of [27, Theorem 3.3], if $f \in {}_0H^\beta(0, T; \dot{H}^\gamma(\Omega))$ with $-1 \leq \gamma \leq 1$ and $0 < \beta \leq 1$, then we have

$$\|u\|_{0H^{\alpha+\beta}(0,T;L^2(\Omega))} + \|u\|_{0H^\beta(0,T;\dot{H}^{2+\gamma}(\Omega))} \leq C_{\alpha,\beta,T} \|f\|_{0H^\beta(0,T;\dot{H}^\gamma(\Omega))}. \quad (14)$$

However, the implicit constant in [27, Lemma 3.2] blows up as the corresponding parameter θ goes to $1/\alpha - 1$ and the estimate in [27, Theorem 3.1] for the homogeneous case $f = 0$ is not optimal. Therefore, in this section, we provide some improved results by using the Mittag-Leffler function [47]

$$E_{\alpha,v}(z) := \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(\alpha k + v)}, \quad z \in \mathbb{C}, \quad v \in \mathbb{R}. \quad (15)$$

Given any $t > 0$, it is well-known that (cf. [23])

$$|E_{\alpha,v}(-t)| \leq \frac{C_{\alpha,v}}{1+t}. \quad (16)$$

In addition, applying Laplace transform gives the solution to (12) with $g = 0$:

$$y(t) = y_0 E_{\alpha,1}(-\lambda t^\alpha), \quad 0 \leq t \leq T. \quad (17)$$

Lemma 3.1 Assume $\lambda \geq \lambda_* > 0$, then the function $y(t)$ defined by (17) satisfies

$$\begin{aligned} \eta(\epsilon) \lambda^{\gamma_0/2-1-\epsilon} \|y\|_{H^\alpha(0,T)} + \lambda^{(\gamma_0-1)/2} \|y\|_{H^{\alpha/2}(0,T)} \\ + \eta(\epsilon) \lambda^{\gamma_0/2-\epsilon} \|y\|_{L^2(0,T)} \leq C_{\alpha,\lambda_*,T} |y_0|, \end{aligned} \quad (18)$$

where

$$\begin{cases} \eta(\epsilon) = 1, & \epsilon = 0, & \text{if } \alpha \neq 1/2, \\ \eta(\epsilon) = \sqrt{\epsilon}, & \epsilon \in (0, 1/2], & \text{if } \alpha = 1/2. \end{cases} \quad (19)$$

Moreover, we have

$$\begin{cases} \epsilon^{3/2} \|y\|_{H^{1/2-\epsilon}(0,T)} \leq C_{\alpha,T} |y_0|, & 0 < \epsilon \leq 1/2, \\ \sqrt{2\gamma - \gamma^2} \|y\|_{H^{(1+\alpha\gamma)/2}(0,T)} \leq C_{\alpha,\lambda_*} \lambda^{\gamma/2} |y_0|, & 0 < \gamma < 2. \end{cases} \quad (20)$$

$$(21)$$

Proof We first prove (18). Since the case $0 < \alpha < 1/2$ has been given by [27, Lemma 3.1], we only consider the case $1/2 \leq \alpha < 1$, which says that

$$\eta(\epsilon) \lambda^{-1-\epsilon} \|y\|_{H^\alpha(0,T)} + \lambda^{-1/2} \|y\|_{H^{\alpha/2}(0,T)} + \eta(\epsilon) \lambda^{-\epsilon} \|y\|_{L^2(0,T)} \leq C_{\alpha,\lambda_*,T} \lambda^{-\frac{1}{2\alpha}} |y_0|. \quad (22)$$

By (16) and direct calculations, we have

$$\begin{aligned} & |\eta(\epsilon)|^2 \lambda^{-2-2\epsilon} |(D_{0+}^\alpha (y - y_0))(t)|^2 + \lambda^{-1} \left| (D_{0+}^{\alpha/2} y)(t) \right|^2 + |\eta(\epsilon)|^2 \lambda^{-2\epsilon} |y(t)|^2 \\ & \leq C_\alpha |y_0|^2 \frac{|\eta(\epsilon)|^2 \lambda^{-2\epsilon} + \lambda^{-1} t^{-\alpha}}{(1 + \lambda t^\alpha)^2}, \end{aligned} \quad (23)$$

for all $0 < t \leq T$. It is evident that

$$\begin{aligned} \int_0^T \frac{\lambda^{-1} t^{-\alpha}}{(1 + \lambda t^\alpha)^2} dt & \leq \int_0^\infty \frac{\lambda^{-1} t^{-\alpha}}{(1 + \lambda t^\alpha)^2} dt \leq \int_0^{\lambda^{-\frac{1}{\alpha}}} \lambda^{-1} t^{-\alpha} dt + \int_{\lambda^{-\frac{1}{\alpha}}}^\infty \lambda^{-3} t^{-3\alpha} dt \\ & = C_\alpha \lambda^{-1/\alpha}. \end{aligned} \quad (24)$$

If $\alpha = 1/2$, then for $0 < \epsilon \leq 1/2$ it holds

$$\int_0^T \frac{\lambda^{-2\epsilon}}{(1 + \lambda t^\alpha)^2} dt = \lambda^{-\frac{1}{\alpha}} \int_0^T \frac{(\lambda t^\alpha)^{1/\alpha-2\epsilon}}{(1 + \lambda t^\alpha)^2} t^{2\alpha\epsilon-1} dt \leq \lambda^{-\frac{1}{\alpha}} \int_0^T t^{2\alpha\epsilon-1} dt = \frac{C_{\alpha,T}}{\epsilon} \lambda^{-1/\alpha};$$

and if $1/2 < \alpha < 1$, then using a similar manner for estimating (24) gives

$$\int_0^T \frac{1}{(1 + \lambda t^\alpha)^2} dt \leq C_\alpha \lambda^{-1/\alpha}.$$

Hence, by Lemma 2.2, plugging the above estimates into (23) implies

$$\eta(\epsilon) \lambda^{-1-\epsilon} \|y - y_0\|_{H^\alpha(0,T)} + \lambda^{-1/2} \|y\|_{H^{\alpha/2}(0,T)} + \eta(\epsilon) \lambda^{-\epsilon} \|y\|_{L^2(0,T)} \leq C_{\alpha,T} \lambda^{-\frac{1}{2\alpha}} |y_0|,$$

which, together with the fact (6) and the assumption $\lambda \geq \lambda_* > 0$, yields (22) immediately.

If $0 < \epsilon \leq 1/2$, then using Lemma 2.1 and 16 gives

$$\begin{aligned} \|y\|_{H^{1/2-\epsilon}(0,T)}^2 & \leq \csc^2 \epsilon \pi \left\| D_{0+}^{1/2-\epsilon} y \right\|_{L^2(0,T)}^2 \leq \frac{C_\alpha |y_0|^2}{\epsilon^2} \int_0^T \frac{t^{2\epsilon-1}}{(1 + \lambda t^\alpha)^2} dt \\ & \leq \frac{C_\alpha |y_0|^2}{\epsilon^2} \int_0^T t^{2\epsilon-1} dt = \frac{C_{\alpha,T} |y_0|^2}{\epsilon^3}, \end{aligned}$$

which proves (20).

To the end, we consider (21). Since $0 < \gamma < 2$, we have $1/2 < (1 + \alpha\gamma)/2 < \alpha + 1/2$. By (16), Lemma 2.2 and straightforward calculations, we get

$$\begin{aligned} \|y - y_0\|_{0H^{(1+\alpha\gamma)/2}(0,T)}^2 &\leq C_\alpha \int_0^T \left| \left(D_{0+}^{(1+\alpha\gamma)/2} (y - y_0) \right) (t) \right|^2 dt \\ &\leq C_\alpha |y_0|^2 \int_0^T \frac{\lambda^2 t^{\alpha(2-\gamma)-1}}{(1 + \lambda t^\alpha)^2} dt, \end{aligned}$$

and we estimate the integral in a similar way for (24) to obtain

$$\|y - y_0\|_{0H^{(1+\alpha\gamma)/2}(0,T)} \leq \frac{C_\alpha \lambda^{\gamma/2} |y_0|}{\sqrt{2\gamma - \gamma^2}}.$$

Therefore, from (6) and the assumption $\lambda \geq \lambda_* > 0$ it follows (21). \square

Remark 3.1 For any fixed $\lambda > 0$, from Lemma 3.1 we see that the highest regularity of $y = y_0 E_{\alpha,1}(-\lambda t^\alpha)$ is no more than $H^{1/2+\alpha}(0, T)$. Although we can establish higher regularity (cf. [34]) for the smooth part $Y = y - y_0 S_\lambda$, where

$$S_\lambda(t) := 1 - \frac{\lambda t^\alpha}{\Gamma(\alpha + 1)}, \quad 0 \leq t \leq T,$$

the final regularity for $y = Y + y_0 S_\lambda$ is dominated by S_λ , which belongs to $H^{1/2+\alpha-\epsilon}(0, T)$ due to the singular term t^α .

Combining Proposition 3.1 and Lemma 3.1 gives the following conclusion.

Theorem 3.1 *If $f = 0$ and $u_0 \in \dot{H}^\gamma(\Omega)$ with $\gamma > 1 - \gamma_0$, then*

$$\begin{aligned} \eta(\epsilon) \|u\|_{H^\alpha(0,T;\dot{H}^{\gamma_0+\gamma-2-\epsilon}(\Omega))} + \|u\|_{H^{\alpha/2}(0,T;\dot{H}^{\gamma_0+\gamma-1}(\Omega))} + \eta(\epsilon) \|u\|_{L^2(0,T;\dot{H}^{\gamma_0+\gamma-\epsilon}(\Omega))} \\ \leq C_{\alpha,T,\Omega} \|u_0\|_{\dot{H}^\gamma(\Omega)}, \end{aligned}$$

where $\epsilon, \eta(\epsilon)$ are defined by (19). Moreover,

$$\begin{cases} \epsilon^{3/2} \|u\|_{H^{1/2-\epsilon}(0,T;L^2(\Omega))} \leq C_{\alpha,T} \|u_0\|_{L^2(\Omega)}, & 0 < \epsilon \leq 1/2, \\ \sqrt{2\gamma - \gamma^2} \|u\|_{H^{(1+\alpha\gamma)/2}(0,T;L^2(\Omega))} \leq C_{\alpha,T,\Omega} \|u_0\|_{\dot{H}^\gamma(\Omega)}, & 0 < \gamma < 2, \\ \sqrt{2\gamma - \gamma^2} \|u\|_{H^{(1+\alpha\gamma)/2}(0,T;\dot{H}^1(\Omega))} \leq C_{\alpha,T,\Omega} \|u_0\|_{\dot{H}^{\gamma+1}(\Omega)}, & 0 < \gamma < 2. \end{cases}$$

3.2 Regularity in Besov Space

We then consider the regularity of the solution to (10) in Besov spaces. As before, we start from the auxiliary problem (12) and split it into two cases: $y_0 \neq 0, g = 0$; and $y_0 = 0, g \neq 0$.

To move on, let us present a useful expression of the Mittag-Leffler function (15); see [15, Theorem 2.1].

Lemma 3.2 [15] *If $\nu < 1 + \alpha$, then for all $0 < t < \infty$, it holds that*

$$E_{\alpha,\nu}(-t) = \frac{1}{\pi\alpha} \int_0^\infty \frac{r \sin \nu\pi - t \sin(\alpha - \nu)\pi}{r^2 + t^2 + 2rt \cos \alpha\pi} r^{(1-\nu)/\alpha} e^{-r^{1/\alpha}} dr.$$

Clearly, by definition (15), we have $E_{\alpha,\nu}(0) = 1/\Gamma(\nu)$ for any $\nu \in \mathbb{R} \setminus \{-1, -2, \dots\}$ and thus $E_{\alpha,\nu}(-t)$ is bounded near $t = 0+$. Below, we give a refined estimate that implies the asymptotic behavior of $E_{\alpha,\nu}(-t)$. Note that this has no contraction with the boundness around $t = 0+$ and what we are interested in is $t \rightarrow \infty$.

Lemma 3.3 *If $v < 1$, then for all $0 < t < \infty$,*

$$|E_{\alpha,v}(-t)| \leq C_{\alpha} \Gamma(1 - v + \theta\alpha) t^{-\theta}, \quad (25)$$

where $0 \leq \theta \leq 1$. Moreover, if $\alpha - v \in \mathbb{Z}$, then (25) holds with $0 \leq \theta \leq 2$.

Proof By Lemma 3.2, we have

$$E_{\alpha,v}(-t) = \frac{1}{\pi\alpha} \int_0^{\infty} r^{(1-v)/\alpha} e^{-r^{1/\alpha}} \varphi_{\alpha,v}(r, t) \, dr, \quad (26)$$

where

$$\varphi_{\alpha,v}(r, t) := \frac{r \sin v\pi - t \sin(\alpha - v)\pi}{r^2 + 2rt \cos \alpha\pi + t^2}.$$

In light of the estimate

$$r^2 + 2rt \cos \alpha\pi + t^2 \geq \frac{1 + \cos \alpha\pi}{2} (r + t)^2 \quad (27)$$

and the arithmetic-geometric mean inequality (cf. [57, page 4])

$$r^{1-\theta} t^{\theta} \leq (1 - \theta)r + \theta t, \quad 0 \leq \theta \leq 1, \quad (28)$$

we obtain that

$$|\varphi_{\alpha,v}(r, t)| \leq \frac{C_{\alpha}}{r + t} \leq C_{\alpha} r^{\theta-1} t^{-\theta}. \quad (29)$$

Therefore, inserting (29) into (26) gives

$$\begin{aligned} |E_{\alpha,v}(-t)| &\leq C_{\alpha} t^{-\theta} \int_0^{\infty} e^{-r^{1/\alpha}} (r^{1/\alpha})^{(\theta-1)\alpha+1-v} \, dr \\ &= C_{\alpha} t^{-\theta} \int_0^{\infty} e^{-s} s^{\theta\alpha-v} \, ds = C_{\alpha} \Gamma(1 + \theta\alpha - v) t^{-\theta}, \end{aligned}$$

which establishes (25). Moreover, if $\alpha - v \in \mathbb{Z}$, then

$$\varphi_{\alpha,v}(r, t) = \frac{r \sin v\pi}{r^2 + 2rt \cos \alpha\pi + t^2},$$

and from (27) and (28) it follows

$$|\varphi_{\alpha,v}(r, t)| \leq C_{\alpha} r^{\theta-1} t^{-\theta}, \quad 0 \leq \theta \leq 2,$$

which maintains the estimate (25) and enlarges the range of θ . This completes the proof. \square

Based on Lemma 3.3, we are able to establish the following lemma.

Lemma 3.4 *Assume $-1 \leq \theta \leq 1$ with $1 + 2\alpha\theta > 0$, then the function y defined by (17) satisfies*

$$\|y\|_{\mathbb{B}_{-\alpha,0}^{1+2\alpha\theta-\epsilon}(0,T)} \leq \frac{C_{\alpha,T}}{\sqrt{\epsilon}} \lambda^{\theta} |y_0|, \quad (30)$$

for any $0 < \epsilon \leq 1 + 2\alpha\theta$.

Proof By (16), it is evident that $y \in L^2_{\mu^{-\alpha,0}}(0, T)$ and we have the orthogonal decomposition $y = \sum_{k=0}^{\infty} y_k S_k^{-\alpha,0}$, where $\{S_k^{-\alpha,0}\}_{k=0}^{\infty}$ denotes the shifted Jacobi polynomials on $(0, T)$ with respect to the weight $\mu^{-\alpha,0}(t) = (T-t)^{-\alpha}$ (see “Appendix A”), and

$$y_k = \frac{1}{\xi_k^{-\alpha,0}} \left\langle y, S_k^{-\alpha,0} \right\rangle_{\mu^{-\alpha,0}}, \quad \xi_k^{-\alpha,0} = \frac{T^{1-\alpha}}{2k+1-\alpha}. \quad (31)$$

According to the definition (8), it suffices to investigate the asymptotic behavior of the coefficient y_k . Let us fix $k \in \mathbb{N}_+$. By Rodrigues’ formula (79), we have

$$\left\langle y, S_k^{-\alpha,0} \right\rangle_{\mu^{-\alpha,0}} = \frac{(-1)^k}{T^k k!} \left\langle y, \frac{d^k}{dt^k} \mu^{k-\alpha,k} \right\rangle_{(0,T)}. \quad (32)$$

Using integration by parts gives

$$\left\langle y, \frac{d^k}{dt^k} \mu^{k-\alpha,k} \right\rangle_{(0,T)} = \sum_{i=0}^{k-1} (-1)^i (\zeta_i(T) - \zeta_i(0)) + (-1)^k \left\langle y^{(k)}, \mu^{k-\alpha,k} \right\rangle_{(0,T)},$$

where

$$\zeta_i(t) = y^{(i)}(t) \left(\frac{d^{k-i-1}}{dt^{k-i-1}} \mu^{k-\alpha,k} \right)(t) = y^{(i)}(t) \sum_{j=0}^{k-i-1} C_{\alpha,i,j,k} \mu^{k-\alpha-j,i+1+j}(t).$$

From (17) we have the identity

$$y^{(i)}(t) = -\lambda y_0 t^{\alpha-i} E_{\alpha,\alpha+1-i}(-\lambda t^\alpha), \quad 0 \leq i < k, \quad (33)$$

and it follows that $\zeta_i(0) = \zeta_i(T) = 0$ for all $0 \leq i < k$. Thus, we obtain the relation

$$\left\langle y, \frac{d^k}{dt^k} \mu^{k-\alpha,k} \right\rangle_{(0,T)} = (-1)^k \left\langle y^{(k)}, \mu^{k-\alpha,k} \right\rangle_{(0,T)}. \quad (34)$$

Invoking (33) and Lemma 3.3 yields the inequality

$$\left| y^{(k)}(t) \right| \leq C_\alpha \Gamma(k - \theta\alpha) |y_0| \lambda^\theta t^{\theta\alpha-k}, \quad (35)$$

where $-1 \leq \theta \leq 1$. In addition, we have a useful formula (cf. [56, Appendix, (A.6)])

$$\left\| \mu^{a,b} \right\|_{L^1(0,T)} = T^{a+b+1} \frac{\Gamma(a+1)\Gamma(b+1)}{\Gamma(a+b+2)}, \quad a, b > -1, \quad (36)$$

which, together with (35), indicates that

$$\begin{aligned} \left| \left\langle y^{(k)}, \mu^{k-\alpha,k} \right\rangle_{(0,T)} \right| &\leq C_\alpha |y_0| \lambda^\theta \Gamma(k - \theta\alpha) \left\| \mu^{k-\alpha,\theta\alpha} \right\|_{L^1(0,T)} \\ &= C_{\alpha,T} |y_0| \lambda^\theta T^k \cdot \frac{\Gamma(k+1-\alpha)\Gamma(k-\theta\alpha)}{\Gamma(k+2+(\theta-1)\alpha)}. \end{aligned} \quad (37)$$

Observe Stirling’s formula [1, Eq. (6.1.38)]

$$\Gamma(z+1) = \sqrt{2\pi} z^{z+1/2} e^{\theta(z)/(12z)-z}, \quad 0 < \theta(z) < 1, \quad z > 0. \quad (38)$$

Therefore, collecting (32), (34) and (37) gives

$$\left| \left\langle y, S_k^{-\alpha,0} \right\rangle_{\mu^{-\alpha,0}} \right| \leq C_{\alpha,T} |y_0| \lambda^\theta \frac{\Gamma(k+1-\alpha)\Gamma(k-\theta\alpha)}{k! \Gamma(k+2+(\theta-1)\alpha)} \leq C_{\alpha,T} |y_0| \lambda^\theta k^{-2-2\theta\alpha}. \quad (39)$$

As a result, for any $0 < \epsilon \leq 1 + 2\alpha\theta$, we have

$$\begin{aligned} & \|y\|_{\mathbb{B}_{-\alpha,0}^{1+2\alpha\theta-\epsilon}(0,T)}^2 \\ &= \sum_{k=0}^{\infty} \frac{1 + k^{2+4\alpha\theta-2\epsilon}}{\xi_k^{-\alpha,0}} \left| \left\langle y, S_k^{-\alpha,0} \right\rangle_{\mu^{-\alpha,0}} \right|^2 \leq C_{\alpha,T} |y_0|^2 \lambda^{2\theta} \left(1 + \sum_{k=1}^{\infty} k^{-1-2\epsilon} \right) \\ &\leq C_{\alpha,T} |y_0|^2 \lambda^{2\theta} \left(1 + \int_1^{\infty} r^{-1-2\epsilon} dr \right) \leq \frac{C_{\alpha,T}}{\epsilon} |y_0|^2 \lambda^{2\theta}, \end{aligned} \quad (40)$$

which shows (30) and finishes the proof of this lemma. \square

Remark 3.2 As mentioned in Remark 3.1, the best regularity of $y(t) = y_0 E_{\alpha,1}(-\lambda t^\alpha)$ is no more than $H^{1/2+\alpha}(0, T)$. However, from Lemma 3.4 we know that $y \in \mathbb{B}_{-\alpha,0}^{1+2\alpha-\epsilon}(0, T)$, which can not be improved due to the singular term t^α , and the optimal rate $1 + 2\alpha$ of the standard Legendre spectral method under L^2 -norm has been validated numerically in Fig. 1.

For another case: $y_0 = 0$, $g \neq 0$, according to [23, Proposition 5.10], the solution y to (12) can be represented as follows

$$y(t) = \int_0^t (t-s)^{\alpha-1} E_{\alpha,\alpha}(-\lambda(t-s)^\alpha) g(s) ds, \quad 0 < t \leq T, \quad (41)$$

and by the proof of [27, Lemma 3.3], if $g \in {}_0H^\beta(0, T)$ with $\beta \geq 0$, then we have

$$\|y\|_{{}_0H^{\alpha+\beta}(0,T)} + \lambda \|y\|_{L^2(0,T)} \leq C_{\alpha,\beta,T} \|g\|_{{}_0H^\beta(0,T)}.$$

In particular, for $g(t) = g_0 t^\sigma$ with $\sigma > -1/2$, a direct computation gives

$$y(t) = \Gamma(\sigma + 1) g_0 t^{\alpha+\sigma} E_{\alpha,\alpha+\sigma+1}(-\lambda t^\alpha), \quad 0 < t \leq T. \quad (42)$$

Analogous to Lemma 3.4, we have the following regularity estimate.

Lemma 3.5 Assume $\sigma > -1/2$ and $0 \leq \theta \leq 1$, then the function y defined by (42) satisfies

$$\|y\|_{\mathbb{B}_{-\alpha,0}^{1+2\sigma+2\alpha\theta-\epsilon}(0,T)} \leq \frac{C_{\alpha,\sigma,T}}{\sqrt{\epsilon}} |g_0| \lambda^{\theta-1}, \quad (43)$$

for all $0 < \epsilon \leq 1 + 2\sigma$. Moreover, if $\alpha + \sigma \in \mathbb{N}$, then we can take $\theta \in [0, 2]$.

Proof Since $\sigma > -1/2$, again by (16), we have $y \in L_{\mu^{-\alpha,0}}^2(0, T)$, and we have the orthogonal decomposition $y = \sum_{k=0}^{\infty} y_k S_k^{-\alpha,0}$, where y_k and $\xi_k^{-\alpha,0}$ are defined in (31).

If $\alpha + \sigma \notin \mathbb{N}$, then

$$y^{(k)}(t) = \Gamma(\sigma + 1) g_0 t^{\alpha+\sigma-k} E_{\alpha,\alpha+\sigma+1-k}(-\lambda t^\alpha) \quad \forall k \in \mathbb{N}. \quad (44)$$

For $k > \alpha + \sigma$, invoking Lemma 3.3 yields the estimate:

$$\left| y^{(k)}(t) \right| \leq C_\alpha \Gamma(\sigma + 1) |g_0| \lambda^{\theta-1} t^{\theta\alpha+\sigma-k} \Gamma(k - \sigma - \theta\alpha), \quad 0 < t \leq T, \quad (45)$$

where $0 \leq \theta \leq 1$. Hence, by using Rodrigues' formula (79) and integration by parts, a similar argument as that for (34) gives

$$\left\langle y, S_k^{-\alpha,0} \right\rangle_{\mu^{-\alpha,0}} = \frac{1}{T^k k!} \left\langle y^{(k)}, \mu^{k-\alpha,k} \right\rangle_{(0,T)}, \quad (46)$$

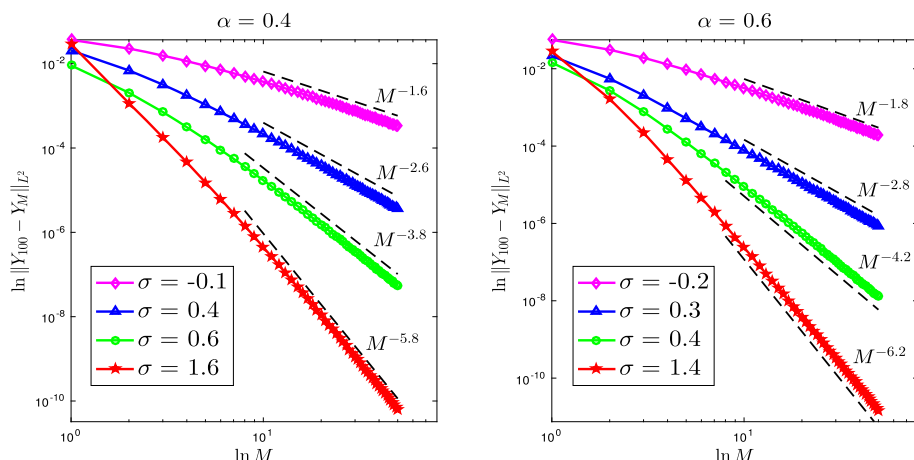


Fig. 2 Discretization errors of (12) with $\lambda = T = 1$, $y_0 = 0$ and $g(t) = t^\sigma$. The predicted accuracies are $M^{-1-2\sigma-2\alpha}$ and $M^{-1-2\sigma-4\alpha}$, respectively for $\sigma + \alpha \notin \mathbb{N}$ and $\sigma + \alpha \in \mathbb{N}$

and from (36) and (45) we obtain

$$\begin{aligned} \left| \frac{1}{T^k k!} \left\langle y^{(k)}, \mu^{k-\alpha, k} \right\rangle_{(0,T)} \right| &\leq C_{\alpha, \sigma} |g_0| \lambda^{\theta-1} \frac{\Gamma(k - \sigma - \theta\alpha)}{T^k \Gamma(k+1)} \left\| \mu^{k-\alpha, \sigma+\theta\alpha} \right\|_{L^1(0,T)} \\ &\leq C_{\alpha, \sigma, T} |g_0| \lambda^{\theta-1} \cdot \frac{\Gamma(k - \alpha + 1)}{\Gamma(k+1)} \cdot \frac{\Gamma(k - \sigma - \theta\alpha)}{\Gamma(k - \alpha + \sigma + \theta\alpha + 2)}. \end{aligned}$$

This together with (38) implies that

$$\left| \left\langle y, S_k^{-\alpha, 0} \right\rangle_{\mu^{-\alpha, 0}} \right| \leq C_{\alpha, \sigma, T} |g_0| \lambda^{\theta-1} k^{-2-2\sigma-2\theta\alpha}. \quad (47)$$

Note that for $k < \alpha + \sigma$, using (16), (28) and (44) gives

$$\left| y^{(k)}(t) \right| \leq C_\alpha \Gamma(\sigma + 1) |g_0| \lambda^{\theta-1} t^{\theta\alpha + \sigma - k}, \quad 0 < t \leq T,$$

where $0 \leq \theta \leq 1$. Thus the estimate (47) holds true for all $k \in \mathbb{N}_+$ and $\theta \in [0, 1]$.

On the other hand, if $\alpha + \sigma \in \mathbb{N}$, then we find that for all $k \in \mathbb{N}$,

$$y^{(k)}(t) = \begin{cases} \Gamma(\sigma + 1) g_0 t^{\alpha + \sigma - k} E_{\alpha, \alpha + \sigma + 1 - k}(-\lambda t^\alpha), & \text{if } k \leq \alpha + \sigma, \\ -\lambda \Gamma(\sigma + 1) g_0 t^{2\alpha + \sigma - k} E_{\alpha, 2\alpha + \sigma + 1 - k}(-\lambda t^\alpha), & \text{if } k > \alpha + \sigma. \end{cases}$$

Thus, we still have the identity (46) and by Lemma 3.3, the estimate (47) holds true for all $k \in \mathbb{N}_+$ and $\theta \in [0, 2]$. Hence, using the proof of (40) leads to the desired estimate (43). \square

To illustrate the maximal regularity in Lemma 3.5, we adopt a standard Legendre spectral method to solve (12) with $\lambda = T = 1$, $y_0 = 0$ and $g(t) = t^\sigma$. In Fig. 2, we report the numerical results under L^2 -norm and observe the convergence rates $M^{-1-2\sigma-2\alpha}$ and $M^{-1-2\sigma-4\alpha}$, respectively for $\alpha + \sigma \notin \mathbb{N}$ and $\alpha + \sigma \in \mathbb{N}$.

Finally, recall Proposition 3.1, which says $u = \sum_{n=0}^{\infty} y_n \phi_n$ with y_n solving the ordinary differential equation (11), and gathering Lemmas 3.4 and 3.5 implies the following regularity results.

Theorem 3.2 If $f = 0$ and $u_0 \in \dot{H}^\gamma(\Omega)$ with $\gamma > 1 - \gamma_0$, then

$$\|u\|_{\mathbb{B}_{-\alpha,0}^{1+\alpha(\gamma-\beta)-\epsilon}(0,T;\dot{H}^\beta(\Omega))} \leq \frac{C_{\alpha,T}}{\sqrt{\epsilon}} \|u_0\|_{\dot{H}^\gamma(\Omega)}, \quad (48)$$

where $\gamma - 2 \leq \beta \leq \gamma + 2$ and $0 < \epsilon \leq 1 + \alpha(\gamma - \beta)$.

Proof By definition, we have

$$\|u\|_{\mathbb{B}_{-\alpha,0}^{1+\alpha(\gamma-\beta)-\epsilon}(0,T;\dot{H}^\beta(\Omega))}^2 = \sum_{n=0}^{\infty} \lambda_n^\beta \|y_n\|_{\mathbb{B}_{-\alpha,0}^{1+\alpha(\gamma-\beta)-\epsilon}(0,T)}^2.$$

Since $u_0 = \sum_{n=0}^{\infty} y_{n,0} \phi_n$ and $y_n = y_{n,0} E_{\alpha,1}(-\lambda_n t^\alpha)$, it follows from Lemma 3.4 that

$$\|u\|_{\mathbb{B}_{-\alpha,0}^{1+\alpha(\gamma-\beta)-\epsilon}(0,T;\dot{H}^\beta(\Omega))}^2 \leq \frac{C_{\alpha,T}}{\epsilon} \sum_{n=0}^{\infty} \lambda_n^\gamma |y_{n,0}|^2 = \frac{C_{\alpha,T}}{\epsilon} \|u_0\|_{\dot{H}^\gamma(\Omega)}^2,$$

provided that $-1 \leq (\gamma - \beta)/2 \leq 1$ and $0 < \epsilon \leq 1 + \alpha(\gamma - \beta)$. \square

Theorem 3.3 Assume $\sigma > -1/2$ and $\gamma \geq -1$. If $u_0 = 0$ and $f = t^\sigma v$ with $v \in \dot{H}^\gamma(\Omega)$, then

$$\|u\|_{\mathbb{B}_{-\alpha,0}^{1+2\sigma+\alpha(2+\gamma-\beta)-\epsilon}(0,T;\dot{H}^\beta(\Omega))} \leq \frac{C_{\alpha,\sigma,T}}{\sqrt{\epsilon}} \|v\|_{\dot{H}^\gamma(\Omega)},$$

where $\gamma \leq \beta \leq 2 + \gamma$ and $0 < \epsilon \leq 1 + 2\sigma$. Particularly, if $\alpha + \sigma \in \mathbb{N}$, then $\gamma - 2 \leq \beta \leq \gamma + 2$.

4 Discretization and Error Analysis

Let \mathcal{K}_h be a conventional conforming and shape regular simplicial triangulation of Ω that consists of d -simplexes, and we use h to denote the maximum diameter of the elements in \mathcal{K}_h . Define

$$X_h := \{v_h \in \dot{H}^1(\Omega) : v_h|_K \in P_1(K) \quad \forall K \in \mathcal{K}_h\}.$$

In the sequel, let $\Omega_T := \Omega \times (0, T)$ and $M \in \mathbb{N}$. The time-spectral method for problem (1) reads as follows: find $U \in P_M(0, T) \otimes X_h$ such that

$$\langle D_{0+}^\alpha U, V \rangle_{H^{\alpha/2}(0,T;L^2(\Omega))} + \langle \nabla U, \nabla V \rangle_{\Omega_T} = \langle f + D_{0+}^\alpha u_0, V \rangle_{P_M(0,T) \otimes X_h} \quad (49)$$

for all $V \in P_M(0, T) \otimes X_h$. It is easy to see that (49) admits a unique solution $U \in P_M(0, T) \otimes X_h$ such that

$$\|U\|_{\mathcal{X}} \leq C_\alpha \|f + D_{0+}^\alpha u_0\|_{\mathcal{X}^*},$$

where the space \mathcal{X} and its norm $\|\cdot\|_{\mathcal{X}}$ are defined in Sect. 3.

We now present our main error estimates. Note that all of the following results are optimal. Also, we emphasize that, in Theorem 4.1, the best temporal convergence orders $1 + \alpha$ and $1 + 2\alpha$ under $H^{\alpha/2}(0, T; L^2(\Omega))$ -norm and $L^2(0, T; \dot{H}^1(\Omega))$ -norm are sharp and cannot be improved even for smoother initial data. As for Theorem 4.2, we restrict ourselves to a special case $f(t, x) = t^\sigma v(x)$, and the obtained temporal convergence rates $1 + 2\sigma + \alpha$ and $1 + 2\sigma + 2\alpha$ are also sharp even for smoother v . Those predictions are verified by our numerical results in Sect. 5.

Theorem 4.1 If $f = 0$ and $u_0 \in \dot{H}^\gamma(\Omega)$ with $1 - \gamma_0 < \gamma \leq 3$, then

$$\|u - U\|_{L^2(0,T;\dot{H}^1(\Omega))} \lesssim \left(\epsilon_h h^{\min\{1,\gamma_0+\gamma-1\}} + M^{-1-\alpha(\gamma-1)} \right) \|u_0\|_{\dot{H}^\gamma(\Omega)}, \quad (50)$$

$$\|u - U\|_{H^{\alpha/2}(0,T;L^2(\Omega))} \lesssim \left(h^{\min\{2,\gamma_0+\gamma-1\}} + M^{-1-\alpha\min\{1,\gamma-1\}} \right) \|u_0\|_{\dot{H}^\gamma(\Omega)}, \quad (51)$$

where $\epsilon_h = 1$ if $\alpha \neq 1/2$, and $\epsilon_h = \sqrt{|\ln h|}$ if $\alpha = 1/2$.

Theorem 4.2 Assume $-1 \leq \gamma \leq 1$ and $\sigma > (\alpha - 1)/2$. If $u_0 = 0$ and $f(t, x) = t^\sigma v(x)$ with $v \in \dot{H}^\gamma(\Omega)$, then

$$\|u - U\|_{H^{\alpha/2}(0,T;L^2(\Omega))} \lesssim \left(h^{\min\{2,\gamma+2\}} + M^{-1-2\sigma-\alpha\min\{1,\gamma+1\}} \right) \|v\|_{\dot{H}^\gamma(\Omega)}, \quad (52)$$

$$\|u - U\|_{L^2(0,T;\dot{H}^1(\Omega))} \lesssim \left(h^{\min\{1,\gamma+1\}} + M^{-1-2\sigma-\alpha(\gamma+1)} \right) \|v\|_{\dot{H}^\gamma(\Omega)}, \quad (53)$$

In addition, if $\alpha + \sigma \in \mathbb{N}$ and $v \in \dot{H}^\gamma(\Omega)$ with $-1 \leq \gamma \leq 3$, then (53) still holds true and the temporal rate in (52) shall be $M^{-1-2\sigma-\alpha\min\{3,\gamma+1\}}$.

Remark 4.1 By Remark 4.4 and the proof of Theorem 4.1, if the true solution is $u(x, t) = t^\sigma \phi(x)$ with $\sigma > (\alpha - 1)/2$ and $\phi \in \dot{H}^2(\Omega)$, then we have

$$\begin{aligned} \|u - U\|_{L^2(0,T;\dot{H}^1(\Omega))} &\lesssim (h + M^{-1-2\sigma}) \|\phi\|_{\dot{H}^2(\Omega)}, \\ \|u - U\|_{H^{\alpha/2}(0,T;L^2(\Omega))} &\lesssim (h^2 + M^{\alpha-1-2\sigma}) \|\phi\|_{\dot{H}^2(\Omega)}. \end{aligned} \quad (54)$$

Remark 4.2 Although in Theorem 4.2 we only give the rigorous error estimates for a special singular right hand side $f = t^\sigma v(x)$, we hope this is helpful for understanding the convergence behavior for general f . Indeed, regardless of the spatial regularity, we conclude that: (i) if f is smooth in time but not vanishing at $t = 0$, then the best temporal convergence rate is $1 + 2\alpha$; if f is smooth (away from the original point) and behaves like t^σ near $t = 0+$, then the best rate is $1 + 2\sigma + 2\alpha$; in addition, if $\alpha + \sigma \in \mathbb{N}$, then we have a faster rate $1 + 2\sigma + 4\alpha$.

4.1 Technical Lemmas

Let $R_h : \dot{H}^1(\Omega) \rightarrow X_h$ be the well-known Ritz projection operator

$$\langle \nabla(I - R_h)v, \nabla v_h \rangle = 0 \quad \forall v_h \in X_h, \quad (55)$$

for which we have the standard estimate [53]

$$\|(I - R_h)v\|_{L^2(\Omega)} + h \|(I - R_h)v\|_{\dot{H}^1(\Omega)} \lesssim h^\gamma \|v\|_{\dot{H}^\gamma(\Omega)} \quad \forall v \in \dot{H}^\gamma(\Omega), \quad 1 \leq \gamma \leq 2.$$

For $a, b > -1$, denote by $\Phi_M^{a,b} : L^2_{\mu^{a,b}}(0, T) \rightarrow P_M(0, T)$ the $L^2_{\mu^{a,b}}$ -orthogonal projection onto $P_M(0, T)$ (cf. “Appendix A”). Assume X is a separable Hilbert space with an orthonormal basis $\{e_n\}_{n=0}^\infty$ and $P_M([0, T]; X)$ is the space of all polynomials (degree $\leq M$) over $(0, T)$ with coefficients in X (see [60]). Following [26, Section 4], we can extend $\Phi_M^{a,b}$ to the vector-valued case $\Phi_{M,X}^{a,b} : L^2_{\mu^{a,b}}(0, T; X) \rightarrow P_M([0, T]; X)$ by that: for all $v = \sum_{n=0}^\infty v_n e_n$ with $v_n \in L^2_{\mu^{a,b}}(0, T)$, define $\Phi_{M,X}^{a,b} v := \sum_{n=0}^\infty e_n \Phi_M^{a,b} v_n$. Clearly, the case $X = \mathbb{R}$ boils down to $\Phi_{M,\mathbb{R}}^{a,b} = \Phi_M^{a,b}$.

Recall that $\{\lambda_n^{-\gamma/2} \phi_n\}_{n=0}^\infty$ is an orthonormal basis of $\dot{H}^\gamma(\Omega)$, and by definition, we claim that

$$\Phi_{M,\dot{H}^\gamma(\Omega)}^{a,b} v = \Phi_{M,L^2(\Omega)}^{a,b} v \quad \forall v \in \dot{H}^\gamma(\Omega), \quad (56)$$

for all $\gamma > 0$. Suppose X and Y are two separable Hilbert spaces and $A : X \rightarrow Y$ is a bounded linear operator. Analogous to [26, Lemma 5.6], we have the commutativity

$$\Phi_{M,Y}^{a,b} A v = A \Phi_{M,X}^{a,b} v \quad \forall v \in L_{\mu^{a,b}}^2(0, T; X). \quad (57)$$

In particular, there holds that

$$\Phi_{M,X_h}^{-\alpha,0} R_h v = R_h \Phi_{M,\dot{H}^1(\Omega)}^{-\alpha,0} v = R_h \Phi_{M,L^2(\Omega)}^{-\alpha,0} v \quad \forall v \in \mathcal{X}. \quad (58)$$

Moreover, by Lemma A.1, for all $v \in \mathcal{X}$,

$$\left\langle D_{0+}^\alpha (I - \Phi_{M,X_h}^{-\alpha,0}) R_h v, V \right\rangle_{H^{\alpha/2}(0,T;L^2(\Omega))} = 0 \quad \forall V \in P_M(0, T) \otimes X_h. \quad (59)$$

This can be verified directly by definition; we also refer to the discussion in [26, Remark 4.2]. For clarity, we provide the detailed proof of (57) in “Appendix B”.

When no confuse arises, we simply write $\Phi_{M,L^2(\Omega)}^{-\alpha,0} u = \Phi_M^{-\alpha,0} u$, where $u = \sum_{n=0}^\infty y_n \phi_n$ is the unique weak solution to (10) and $y_n \in H^{\alpha/2}(0, T)$. By the stability estimate (85), we have that

$$\left\| \Phi_M^{-\alpha,0} u \right\|_{H^{\alpha/2}(0,T;\dot{H}^\gamma(\Omega))} \lesssim \|u\|_{H^{\alpha/2}(0,T;\dot{H}^\gamma(\Omega))}, \quad 0 \leq \gamma \leq 2, \quad (60)$$

and moreover,

$$u - \Phi_M^{-\alpha,0} u = \sum_{n=0}^\infty \phi_n (I - \Phi_M^{-\alpha,0}) y_n, \quad (61)$$

which means the projection error of u is related to the scalar case $(I - \Phi_M^{-\alpha,0}) y_n$, where y_n solves the ordinary differential equation (11).

In what follows, we give some nontrivial projection error bounds in terms of the solution to (12). The decay estimates of y_k established in Lemmas 3.4 and 3.5 are enough to provide optimal rate in the $L_{\mu^{-\alpha,0}}^2(0, T)$ -norm. Moreover, we shall utilize it to prove the error estimate under the fractional norm $|\cdot|_{H^{\alpha/2}(0,T)}$.

Lemma 4.1 *Let y be given by (17) with $\lambda > 0$ and $y_0 \in \mathbb{R}$, then*

$$\left\| (I - \Phi_M^{-\alpha,0}) y \right\|_{L_{\mu^{-\alpha,0}}^2(0,T)} \leq C_{\alpha,T} |y_0| \lambda^\theta M^{-1-2\alpha\theta}, \quad (62)$$

where $-1 \leq \theta \leq 1$ and $1 + 2\alpha\theta > 0$.

Proof According to the proof of Lemma 3.4,

$$\left\| (I - \Phi_M^{-\alpha,0}) y \right\|_{L_{\mu^{-\alpha,0}}^2(0,T)}^2 = \sum_{k=M+1}^\infty |y_k|^2 \xi_k^{-\alpha,0} \leq C_{\alpha,T} \sum_{k=M+1}^\infty \frac{|y_k|^2}{k},$$

where y_k and $\xi_k^{-\alpha,0}$ are defined by (31). Thanks to (39), we have

$$\begin{aligned} \left\| (I - \Phi_M^{-\alpha,0}) y \right\|_{L_{\mu^{-\alpha,0}}^2(0,T)}^2 &\leq C_{\alpha,T} |y_0|^2 \lambda^{2\theta} \sum_{k=M+1}^\infty k^{-3-4\theta\alpha} \\ &\leq C_{\alpha,T} |y_0|^2 \lambda^{2\theta} \int_M^\infty r^{-3-4\theta\alpha} dr = C_{\alpha,T} |y_0|^2 \lambda^{2\theta} M^{-2-4\theta\alpha}. \end{aligned} \quad (63)$$

This establishes (62) and finishes the proof of this lemma. \square

Remark 4.3 It is clear that $L^2_{\mu^{-\alpha,0}}(0, T) \hookrightarrow L^2(0, T)$. Hence, we conclude from Lemma 4.1 that

$$\left\| (I - \Phi_M^{-\alpha,0})y \right\|_{L^2(0,T)} \leq C_{\alpha,T} |y_0| \lambda^\theta M^{-1-2\alpha\theta},$$

where $-1 \leq \theta \leq 1$ and $1 + 2\alpha\theta > 0$.

Lemma 4.2 Let y be given by (17) with $\lambda > 0$ and $y_0 \in \mathbb{R}$, then

$$\left| (I - \Phi_M^{-\alpha,0})y \right|_{H^{\alpha/2}(0,T)} \leq C_{\alpha,T} |y_0| \lambda^\theta M^{\alpha-1-2\alpha\theta}, \quad (64)$$

where $-1 \leq \theta \leq 1$ and $1 + 2\alpha\theta > \alpha$.

Proof By (18), we see $y \in H^{\alpha/2}(0, T)$ and from [17, Theorem 1.4.4.3], we know that $v \in L^2_{\mu^{-\alpha}}(0, T)$, where $\mu^{-\alpha}(t) = (T - t)^{-\alpha} t^{-\alpha}$. Recall the coefficient y_k defined by (31) and set $z := (I - \Phi_M^{-\alpha,0})y = \sum_{k=M+1}^{\infty} y_k S_k^{-\alpha,0}$. By (82), we have

$$D_{0+}^{\alpha/2} z = \sum_{k=M+1}^{\infty} \frac{y_k \Gamma(k+1)}{\Gamma(k+1-\alpha/2)} t^{-\alpha/2} S_k^{-\alpha/2}. \quad (65)$$

Here, we changed the order of the summation and the fractional derivative operator and the identity (65) holds true in $L^2(0, T)$. To verify this, it is enough to check that $D_{0+}^{\alpha/2} y = \sum_{k=0}^{\infty} y_k D_{0+}^{\alpha/2} S_k^{-\alpha,0}$ in $L^2(0, T)$. Indeed, this follows from Lemma 2.1 and the fact $\lim_{M \rightarrow \infty} \|(I - \Phi_M^{-\alpha,0})y\|_{H^{\alpha/2}(0,T)} = 0$; see Lemma A.1.

On the other hand, since $z \in L^2_{\mu^{0,-\alpha}}(0, T)$, we have the orthogonal expansion (see (81)):

$$z = \sum_{k=0}^{\infty} z_k S_k^{0,-\alpha} \quad \text{with } z_k = \frac{2k+1-\alpha}{T^{1-\alpha}} \left\langle z, S_k^{0,-\alpha} \right\rangle_{\mu^{0,-\alpha}},$$

and it follows from (83) that

$$D_{T-}^{\alpha/2} z = \sum_{k=0}^{\infty} \frac{z_k \Gamma(k+1)}{\Gamma(k+1-\alpha/2)} (T-t)^{-\alpha/2} S_k^{-\alpha/2}.$$

Similar with (65), this holds true in $L^2(0, T)$. Hence, from Lemma 2.1 and the orthogonality of $\{S_k^{-\alpha/2}\}_{k=0}^{\infty}$ with respect to the weight $\mu^{-\alpha/2}(t) = (T-t)^{-\alpha/2} t^{-\alpha/2}$, we obtain

$$\cos(\alpha\pi/2) |z|_{H^{\alpha/2}(0,T)}^2 = \left\langle D_{0+}^{\alpha/2} z, D_{T-}^{\alpha/2} z \right\rangle_{(0,T)} = \sum_{k=M+1}^{\infty} \frac{y_k z_k \Gamma(k+1) T^{1-\alpha}}{(2k+1-\alpha) \Gamma(k+1-\alpha)}. \quad (66)$$

By Rodrigues' formula (79), we have

$$y_k = (-1)^k \frac{2k+1-\alpha}{T^{k+1-\alpha} k!} \left\langle y, \frac{d^k}{dt^k} \mu^{k-\alpha,k} \right\rangle_{(0,T)},$$

$$z_k = (-1)^k \frac{2k+1-\alpha}{T^{k+1-\alpha} k!} \left\langle z, \frac{d^k}{dt^k} \mu^{k,k-\alpha} \right\rangle_{(0,T)}.$$

It follows from (32) and (34) that

$$\left\langle y, \frac{d^k}{dt^k} \mu^{k-\alpha, k} \right\rangle_{(0,T)} = (-1)^k \left\langle y^{(k)}, \mu^{k-\alpha, k} \right\rangle_{(0,T)}.$$

When $k \geq M+1$, we have $z^{(k)}(t) = y^{(k)}(t)$. Therefore, applying the proof of (34) gives

$$\left\langle z, \frac{d^k}{dt^k} \mu^{k, k-\alpha} \right\rangle_{(0,T)} = (-1)^k \left\langle y^{(k)}, \mu^{k, k-\alpha} \right\rangle_{(0,T)}.$$

Substituting the above two identities into (66) implies

$$\cos(\alpha\pi/2) |z|_{H^{\alpha/2}(0,T)}^2 = \sum_{k=M+1}^{\infty} \frac{2k+1-\alpha}{T^{1-\alpha}} \cdot \frac{\langle y^{(k)}, \mu^{k-\alpha, k} \rangle_{(0,T)}}{T^k \Gamma(k+1-\alpha)} \cdot \frac{\langle y^{(k)}, \mu^{k, k-\alpha} \rangle_{(0,T)}}{T^k \Gamma(k+1)}. \quad (67)$$

In view of (37), it follows that

$$\frac{\langle y^{(k)}, \mu^{k-\alpha, k} \rangle_{(0,T)}}{T^k \Gamma(k+1-\alpha)} \leq C_{\alpha, T} \cdot \frac{|y_0| \lambda^\beta \Gamma(k-\beta\alpha)}{\Gamma(k+2+(\beta-1)\alpha)}, \quad (68)$$

for all $-1 \leq \beta \leq 1$. Analogously, one has

$$\frac{\langle y^{(k)}, \mu^{k, k-\alpha} \rangle_{(0,T)}}{T^k \Gamma(k+1)} \leq C_{\alpha, T} \cdot \frac{|y_0| \lambda^\gamma \Gamma(k-\gamma\alpha)}{\Gamma(k+2+(\gamma-1)\alpha)}, \quad (69)$$

for arbitrary $-1 \leq \gamma \leq 1$.

Consequently, plugging the above two estimates into (67) and applying Stirling's formula (38) yield that

$$\begin{aligned} |z|_{H^{\alpha/2}(0,T)}^2 &\leq C_{\alpha, T} |y_0|^2 \lambda^{\beta+\gamma} \sum_{k=M+1}^{\infty} \frac{k \Gamma(k-\beta\alpha)}{\Gamma(k+2+(\beta-1)\alpha)} \cdot \frac{\Gamma(k-\gamma\alpha)}{\Gamma(k+2+(\gamma-1)\alpha)} \\ &\leq C_{\alpha, T} |y_0|^2 \lambda^{\beta+\gamma} \sum_{k=M+1}^{\infty} k^{2\alpha-3-2\alpha(\beta+\gamma)}. \end{aligned}$$

Let $\theta = (\beta+\gamma)/2 \in [-1, 1]$ be such that $1+2\alpha\theta > \alpha$. Then using the proof of (63) implies the desired estimate (64) and concludes the proof of this lemma. \square

Remark 4.4 To get (64), the key is to establish (68) and (69), which are easy to obtain for the singular function $y(t) = t^\sigma$. Hence, according to the proofs of Lemmas 4.1 and 4.2, it is not hard to conclude the following estimate:

$$\left\| (I - \Phi_M^{-\alpha, 0}) y \right\|_{L_{\mu^{-\alpha, 0}}^2(0,T)} + M^{-\alpha} \left\| (I - \Phi_M^{-\alpha, 0}) y \right\|_{H^{\alpha/2}(0,T)} \leq C_{\alpha, \sigma, T} M^{-1-2\sigma},$$

where $\sigma > (\alpha-1)/2$. We mention that the optimal rate $1+2\sigma$ of the Legendre projection under L^2 -norm has already been proved in [18, Theorem 5]. See also some similar results in [61, Lemma 3.3 and Theorem 3.5] for the estimate of $(I - \Phi_M^{\alpha, 0})y$ under the weighted $L_{\mu^{\alpha, 0}}^2$ -norm.

For the particular case: $y_0 = 0$, $g(t) = g_0 t^\sigma$, we can also prove optimal projection error bounds for the solution to the auxiliary problem (12). Indeed, by the previous two estimates

(45) and (47), we are able to establish the corresponding key results like (68) and (69). Since the proof techniques are almost the same as that of Lemmas 4.1 and 4.2, we omit the details and only list the main results as follows.

Lemma 4.3 *Let y be given by (42) with $g_0 \in \mathbb{R}$, $\lambda > 0$ and $\sigma > -1/2$. Then for any $0 \leq \theta \leq 1$, we have*

$$\left\| (I - \Phi_M^{-\alpha,0})y \right\|_{L^2_{\mu^{-\alpha,0}}(0,T)} \leq C_{\alpha,\sigma,T} |g_0| \lambda^{\theta-1} M^{-1-2\sigma-2\theta\alpha}, \quad (70)$$

and if $\sigma > (\alpha - 1)/2$, then

$$\left| (I - \Phi_M^{-\alpha,0})y \right|_{H^{\alpha/2}(0,T)} \leq C_{\alpha,\sigma,T} |g_0| \lambda^{\theta-1} M^{\alpha-1-2\sigma-2\theta\alpha}. \quad (71)$$

Moreover, if $\alpha + \sigma \in \mathbb{N}$, then we can take $\theta \in [0, 2]$ for both (70) and (71).

Below, we present a lemma that connects the above projection errors with our desired estimates. Recall that the space \mathcal{X} is given in (9) and \mathcal{X}^* denotes its dual space.

Lemma 4.4 *If $f + D_{0+}^\alpha u_0 \in \mathcal{X}^*$, then*

$$\begin{aligned} \|u - U\|_{H^{\alpha/2}(0,T;L^2(\Omega))} &\leq \left\| (I - \Phi_M^{-\alpha,0})u \right\|_{\mathcal{X}} + \|(I - R_h)u\|_{H^{\alpha/2}(0,T;L^2(\Omega))} \\ &\quad + \left\| (I - R_h)\Phi_M^{-\alpha,0}u \right\|_{H^{\alpha/2}(0,T;L^2(\Omega))}, \end{aligned} \quad (72)$$

and moreover,

$$\|u - U\|_{L^2(0,T;\dot{H}^1(\Omega))} \lesssim \|(I - R_h)u\|_{\mathcal{X}} + \left\| (I - \Phi_M^{-\alpha,0})u \right\|_{L^2(0,T;\dot{H}^1(\Omega))}. \quad (73)$$

Proof By (10), for any $V \in P_M(0, T) \otimes X_h$, we have

$$\langle D_{0+}^\alpha u, V \rangle_{H^{\alpha/2}(0,T;L^2(\Omega))} + \langle \nabla u, \nabla V \rangle_{\Omega_T} = \langle f + D_{0+}^\alpha u_0, V \rangle_{\mathcal{X}},$$

which, together with (49), gives the error equation

$$\langle D_{0+}^\alpha (u - U), V \rangle_{H^{\alpha/2}(0,T;L^2(\Omega))} + \langle \nabla (u - U), \nabla V \rangle_{\Omega_T} = 0 \quad \forall V \in P_M(0, T) \otimes X_h. \quad (74)$$

Hence it follows that

$$\begin{aligned} \langle D_{0+}^\alpha (U - W), V \rangle_{H^{\alpha/2}(0,T;L^2(\Omega))} + \langle \nabla (U - W), \nabla V \rangle_{\Omega_T} \\ = \langle D_{0+}^\alpha (u - W), V \rangle_{H^{\alpha/2}(0,T;L^2(\Omega))} + \langle \nabla (u - W), \nabla V \rangle_{\Omega_T}, \end{aligned}$$

where $W = \Phi_{M,X_h}^{-\alpha,0} R_h u$. Applying (55) and (59) and the fact $\Phi_{M,X_h}^{-\alpha,0} R_h u = R_h \Phi_M^{-\alpha,0} u$ (cf. (58)) yields the identity

$$\begin{aligned} \langle D_{0+}^\alpha (U - W), V \rangle_{H^{\alpha/2}(0,T;L^2(\Omega))} + \langle \nabla (U - W), \nabla V \rangle_{\Omega_T} \\ = \langle D_{0+}^\alpha (u - R_h u), V \rangle_{H^{\alpha/2}(0,T;L^2(\Omega))} + \left\langle \nabla (I - \Phi_M^{-\alpha,0})u, \nabla V \right\rangle_{\Omega_T}, \end{aligned}$$

and thus taking $V = U - W$ implies

$$\|U - W\|_{\mathcal{X}} \lesssim \|(I - R_h)u\|_{H^{\alpha/2}(0,T;L^2(\Omega))} + \left\| (I - \Phi_M^{-\alpha,0})u \right\|_{L^2(0,T;\dot{H}^1(\Omega))}.$$

Now using the triangle inequality and the stability result (85) gives

$$\begin{aligned} \|u - U\|_{H^{\alpha/2}(0,T;L^2(\Omega))} &\lesssim \|u - W\|_{H^{\alpha/2}(0,T;L^2(\Omega))} + \|U - W\|_{H^{\alpha/2}(0,T;L^2(\Omega))} \\ &\lesssim \left\| (I - \Phi_M^{-\alpha,0})u \right\|_{H^{\alpha/2}(0,T;L^2(\Omega))} \\ &\quad + \left\| (I - R_h)\Phi_M^{-\alpha,0}u \right\|_{H^{\alpha/2}(0,T;L^2(\Omega))} + \|U - W\|_{\mathcal{X}} \\ &\lesssim \left\| (I - \Phi_M^{-\alpha,0})u \right\|_{\mathcal{X}} + \left\| (I - R_h)\Phi_M^{-\alpha,0}u \right\|_{H^{\alpha/2}(0,T;L^2(\Omega))} \\ &\quad + \|(I - R_h)u\|_{H^{\alpha/2}(0,T;L^2(\Omega))}. \end{aligned}$$

This establishes (72). Since (73) can be proved similarly, we conclude the proof. \square

4.2 Proofs of Theorems 4.1 and 4.2

As the proof of Theorem 4.2 is parallel to that of Theorem 4.1, we only consider the latter.

Proof of Theorem 4.1 According to Theorem 3.1, we have

$$\begin{aligned} \|(I - R_h)u\|_{L^2(0,T;\dot{H}^1(\Omega))} &\lesssim \begin{cases} \frac{1}{\sqrt{\epsilon}} h^{\min\{1,\gamma+1\}-\epsilon} \|u_0\|_{\dot{H}^\gamma(\Omega)}, & \alpha = 1/2, \\ h^{\min\{1,\gamma_0+\gamma-1\}} \|u_0\|_{\dot{H}^\gamma(\Omega)}, & \alpha \neq 1/2, \end{cases} \\ \|(I - R_h)u\|_{H^{\alpha/2}(0,T;L^2(\Omega))} &\lesssim h^{\min\{2,\gamma_0+\gamma-1\}} \|u_0\|_{\dot{H}^\gamma(\Omega)}. \end{aligned}$$

For $\alpha = 1/2$, we choose $\epsilon = 1/(2 + |\ln h|)$ to get

$$\|(I - R_h)u\|_{L^2(0,T;\dot{H}^1(\Omega))} \lesssim \sqrt{|\ln h|} h^{\min\{1,\gamma+1\}} \|u_0\|_{\dot{H}^\gamma(\Omega)}.$$

Besides, there holds that

$$\left\| (I - R_h)\Phi_M^{-\alpha,0}u \right\|_{H^{\alpha/2}(0,T;L^2(\Omega))} \lesssim h^{\min\{2,\gamma_0+\gamma-1\}} \left\| \Phi_M^{-\alpha,0}u \right\|_{H^{\alpha/2}(0,T;\dot{H}^{\gamma_0+\gamma-1}(\Omega))}.$$

Thanks to Theorem 3.1 and (60), we obtain

$$\left\| (I - R_h)\Phi_M^{-\alpha,0}u \right\|_{H^{\alpha/2}(0,T;L^2(\Omega))} \lesssim h^{\min\{2,\gamma_0+\gamma-1\}} \|u_0\|_{\dot{H}^\gamma(\Omega)}.$$

Invoking (61), Proposition 3.1, Lemma 4.1, and Remark 4.3 gives the estimate

$$\left\| (I - \Phi_M^{-\alpha,0})u \right\|_{L^2(0,T;\dot{H}^1(\Omega))} \lesssim M^{-1-\alpha(\gamma-1)} \|u_0\|_{\dot{H}^\gamma(\Omega)},$$

and similarly, by Lemma 4.2 we conclude that

$$\left\| (I - \Phi_M^{-\alpha,0})u \right\|_{\mathcal{X}} \lesssim M^{-1-\alpha \min\{1,\gamma-1\}} \|u_0\|_{\dot{H}^\gamma(\Omega)}.$$

Combining these estimates with Lemma 4.4 leads to (51) and (50). This completes the proof of Theorem 4.1. \square

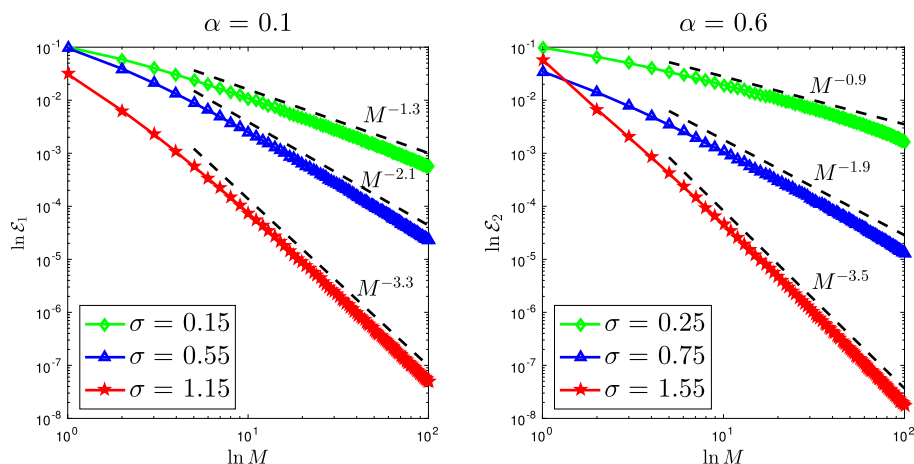


Fig. 3 Temporal errors of Example 1 with $h = 2^{-10}$

5 Numerical Tests

This section presents several numerical experiments to validate our theoretical predictions. For simplicity, we take $T = 1$, $\Omega = (0, 1)$ or $(0, 1)^2$. As spatial discretization errors have been investigated in [27], we are concerned with the temporal convergence behaviors of

$$\mathcal{E}_1 := \|\hat{u} - U\|_{L^2(0,T;\dot{H}^1(\Omega))} \quad \text{and} \quad \mathcal{E}_2 := \|\hat{u} - U\|_{H^{\alpha/2}(0,T;L^2(\Omega))},$$

where \hat{u} is the reference solution.

5.1 One-Dimensional Tests

We first consider three experiments in one spatial dimension: $\Omega = (0, 1)$. The reference solution \hat{u} corresponds to $M = 200$ and $h = 2^{-10}$.

Example 1 This example is to verify Remark 4.1 with a priori known solution

$$u(x, t) = t^\sigma \sin \pi x, \quad (x, t) \in \Omega_T,$$

where $\sigma > (\alpha - 1)/2$. Temporal discretization errors are plotted in Fig. 3, which shows $\mathcal{E}_1 = O(M^{-1-2\sigma})$ and $\mathcal{E}_2 = O(M^{\alpha-1-2\sigma})$. This agrees well with the rates given in (54).

Example 2 To verify Theorem 4.1, we consider $f = 0$ and

$$u_0(x) = \theta x(1-x)^{\gamma-1/2} + (1-\theta) \sin \pi x, \quad x \in \Omega,$$

where $1 - \gamma_0 < \gamma \leq 1.5$ and $\theta \in \{0, 1\}$. For $\theta = 1$, a direct calculation yields that $u_0 \in \dot{H}^{\gamma-\epsilon}(\Omega)$; and for $\theta = 0$, we have $u_0 \in \dot{H}^\beta(\Omega)$ with any $\beta > 0$, since $\sin \pi x$ is an eigenfunction of $-\Delta$ on $\Omega = (0, 1)$ with the homogeneous Dirichlet boundary condition. Numerical outputs are plotted in Fig. 4, which implies that $\mathcal{E}_1 = O(M^{-1-\alpha \min\{2, \gamma-1\}})$ and $\mathcal{E}_2 = O(M^{-1-\alpha \min\{1, \gamma-1\}})$. These coincide with the sharp estimates established in Theorem 4.1.

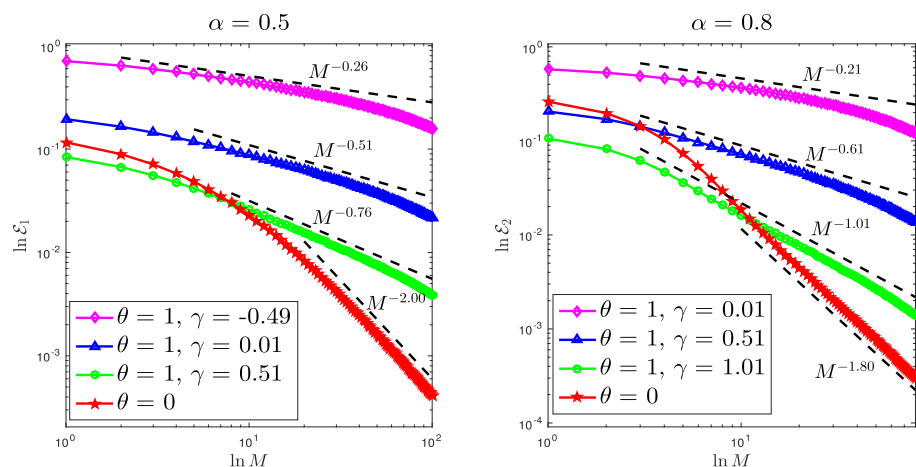


Fig. 4 Temporal errors of Example 2 with $h = 2^{-10}$

Example 3 This example is to verify Theorem 4.2 with $u_0 = 0$ and $f(x, t) = t^\sigma v(x)$, where $\sigma > (\alpha - 1)/2$ and

$$v(x) = \theta x^{\gamma-1/2}(1-x) + (1-\theta) \sin \pi x, \quad x \in \Omega,$$

with $-0.5 < \gamma \leq 1.5$ and $\theta \in \{0, 1\}$.

We first consider $\alpha + \sigma \notin \mathbb{N}$ and $\theta = 1$. Note that $v \in \dot{H}^{\gamma-\epsilon}(\Omega)$ and from Fig. 5 we conclude that

$$\mathcal{E}_1 = O\left(M^{-1-2\sigma-\alpha \min\{2, \gamma+1\}}\right) \quad \text{and} \quad \mathcal{E}_2 = O\left(M^{-1-2\sigma-\alpha \min\{1, \gamma+1\}}\right). \quad (75)$$

Then we take $\alpha + \sigma \in \mathbb{N}$ and $\theta = 0$. In this situation, we have $v \in \dot{H}^\beta(\Omega)$ with any $\beta > 0$ and according to Fig. 6, we observe faster convergence rates

$$\mathcal{E}_1 = O(M^{-1-2\sigma-4\alpha}) \quad \text{and} \quad \mathcal{E}_2 = O(M^{-1-2\sigma-3\alpha}). \quad (76)$$

Both this and the previous case are conformable to the sharp error bounds in Theorem 4.2.

5.2 Two-Dimensional Tests

We provide two more examples in two spatial dimensions: $\Omega = (0, 1)^2$. The reference solution \hat{u} corresponds to $M = 120$ and $h = 2^{-5}$.

For $\theta \in \{1, 2, 3\}$ and any $x = (x_1, x_2) \in \Omega$, define

$$v(x) := \begin{cases} \delta_z(x) & \text{if } \theta = 1, \\ \chi_{\{0 < x_1 < 1/2\}}(x) & \text{if } \theta = 2, \\ \sin(\pi x_1) \sin(\pi x_2) & \text{if } \theta = 3, \end{cases} \quad (77)$$

where δ_z denotes the Dirac distribution centered at $z = (1/2, 1/2) \in \Omega$ and χ_ω is the indicator function of the region ω , i.e., $\chi(x) = 1$ for $x \in \omega$ and $\chi(x) = 0$ for $x \notin \omega$. It is not hard to

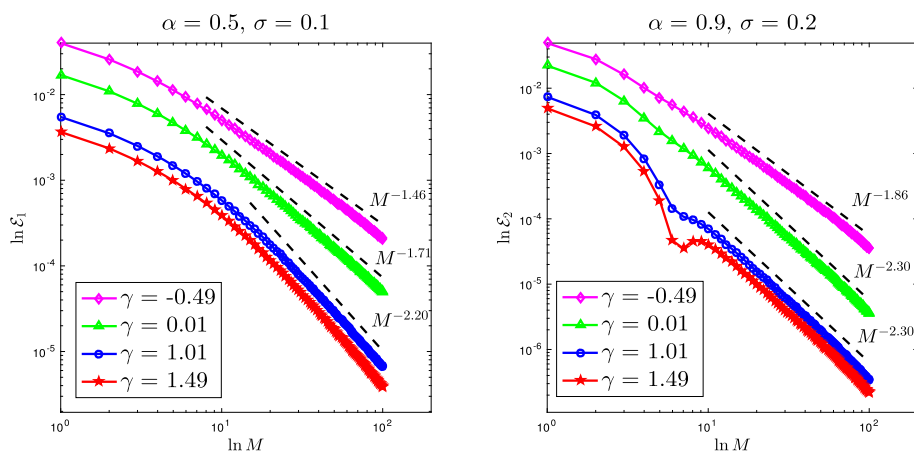


Fig. 5 Temporal errors of Example 3 with $\theta = 1$ and $h = 2^{-10}$

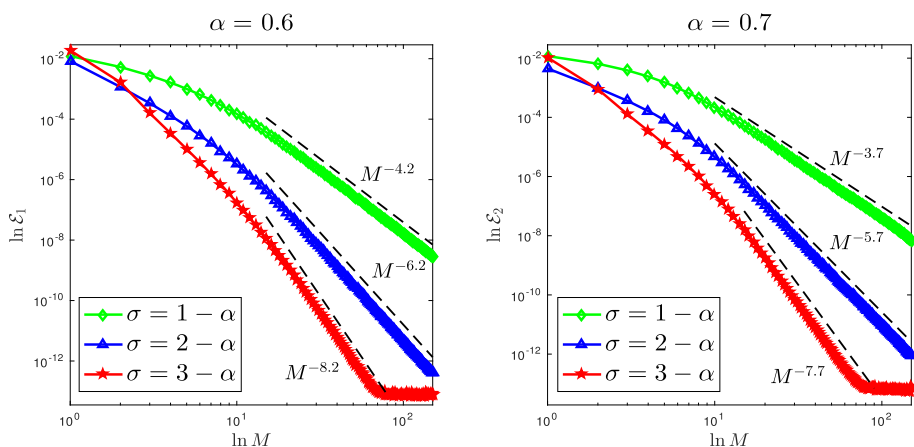


Fig. 6 Temporal errors of Example 3 with $\theta = 0$ and $h = 2^{-10}$

find that $v \in \dot{H}^{\gamma(\theta)-\epsilon}(\Omega)$, where

$$\gamma(\theta) := \begin{cases} -1 & \text{if } \theta = 1, \\ 1/2 & \text{if } \theta = 2, \\ \gamma \in (3, \infty) & \text{if } \theta = 3. \end{cases} \quad (78)$$

Example 4 In this test, we take $f = 0$ and $u_0 = v$ with v being defined in (77). From Fig. 7, we see that $\mathcal{E}_1 = O(M^{-1-\alpha \min\{2, \gamma(\theta)-1\}})$ and $\mathcal{E}_2 = O(M^{-1-\alpha \min\{1, \gamma(\theta)-1\}})$ for $\theta \in \{2, 3\}$, where $\gamma(\theta)$ is defined by (78). This verifies the estimates in Theorem 4.1.

Example 5 To the end, we consider $u_0 = 0$ and $f(x, t) = t^\sigma v(x)$ where $\sigma > (\alpha - 1)/2$ and v is defined in (77). In Fig. 8, we report the numerical results in (75) for $\alpha + \sigma \notin \mathbb{N}$ and observe the same rates, with γ being $\gamma(\theta)$ (cf. (78)). The case $\theta = 3$, $\alpha + \sigma \in \mathbb{N}$ has also been displayed in Fig. 9, which yields the same faster rates as in (76). These agree well with the theoretical predictions in Theorem 4.2.

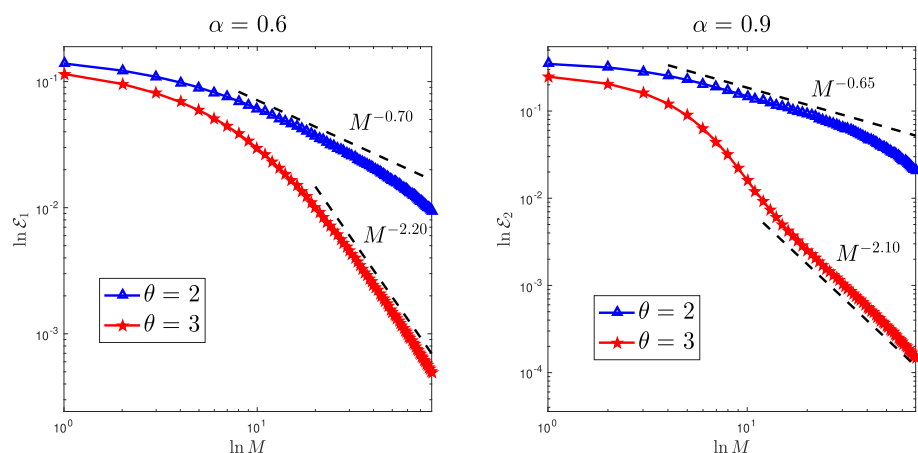


Fig. 7 Temporal errors of Example 4 with $h = 2^{-5}$

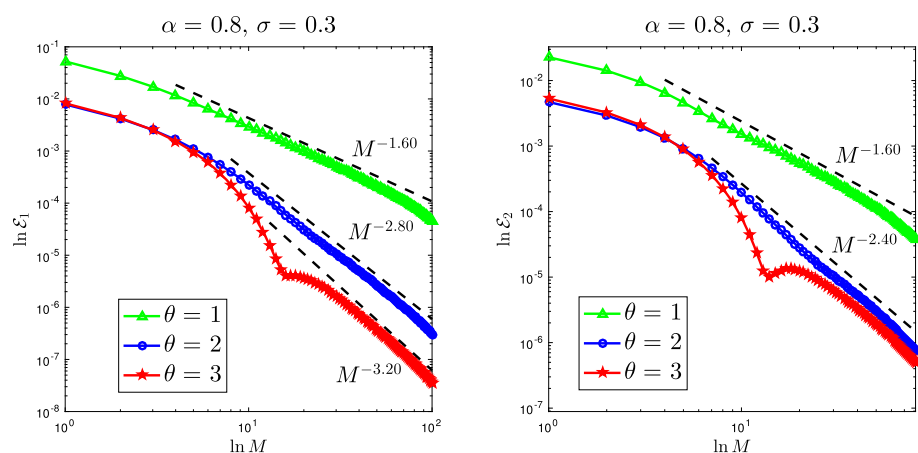


Fig. 8 Temporal errors of Example 5 with $h = 2^{-5}$

6 Conclusion

This paper is devoted to sharp error estimates of a time-spectral algorithm for time fractional diffusion problems of order α ($0 < \alpha < 1$). Based on new regularity results in the Besov space, optimal convergence rates have been derived with low regularity data. Particularly, for the homogenous case $f = 0$, optimal temporal convergence orders $1 + 2\alpha$ and $1 + \alpha$ under $L^2(0, T; \dot{H}^1(\Omega))$ -norm and $H^{\alpha/2}(0, T; L^2(\Omega))$ -norm have been shown theoretically and numerically.

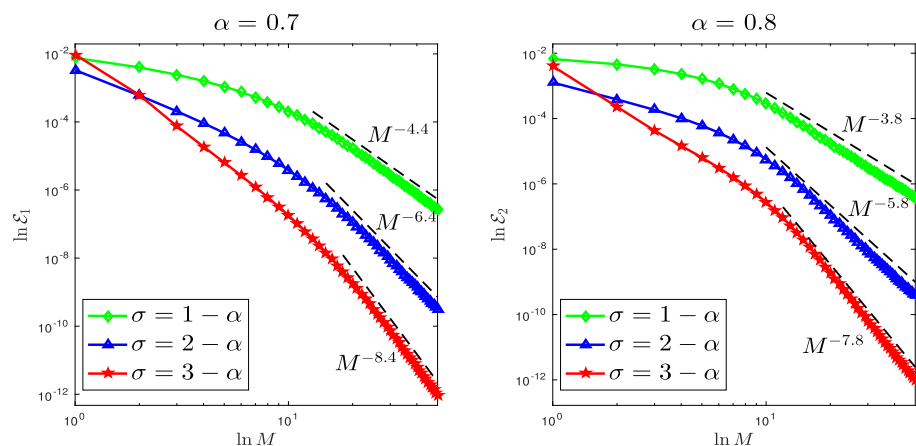


Fig. 9 Temporal errors of Example 5 with $\theta = 3$ and $h = 2^{-5}$

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Declarations

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A The Shifted Jacobi Polynomial

Given $a, b > -1$, the family of shifted Jacobi polynomial $\{S_k^{a,b}\}_{k=0}^{\infty}$ on $(0, T)$ are defined as follows:

$$\mu^{a,b}(t) S_k^{a,b}(t) = \frac{(-1)^k}{T^k k!} \frac{d^k}{dt^k} \mu^{k+a, k+b}(t), \quad 0 < t < T, \quad (79)$$

where $\mu^{v,\theta}(t) = (T-t)^v t^\theta$ for all $-1 < v, \theta < \infty$. Note that (79) is also called Rodrigues' formula [56], which implies $\{S_k^{a,b}\}_{k=0}^{\infty}$ is orthogonal with respect to the weight $\mu^{a,b}$ on $(0, T)$, i.e.,

$$\left\langle S_k^{a,b}, S_l^{a,b} \right\rangle_{\mu^{a,b}} = \xi_k^{a,b} \delta_{kl},$$

where δ_{kl} denotes the Kronecker product and

$$\xi_k^{a,b} := \frac{T^{a+b+1} \Gamma(k+a+1) \Gamma(k+b+1)}{(2k+a+b+1) k! \Gamma(k+a+b+1)}. \quad (80)$$

As $\{S_k^{a,b}\}_{k=0}^{\infty}$ forms a complete orthogonal basis of $L_{\mu^{a,b}}^2(0, T)$, any $v \in L_{\mu^{a,b}}^2(0, T)$ admits a unique decomposition

$$v = \sum_{k=0}^{\infty} v_k S_k^{a,b} \quad \text{with } v_k = \frac{1}{\xi_k^{a,b}} \left\langle v, S_k^{a,b} \right\rangle_{\mu^{a,b}}, \quad (81)$$

and the $L^2_{\mu^{a,b}}$ -orthogonal projection of v onto $P_M(0, T)$ is defined as $\Phi_M^{a,b} v := \sum_{k=0}^M v_k S_k^{a,b}$. For ease of notation, we shall set $S_k^a = S_k^{a,a}$, $\mu^a = \mu^{a,a}$, $\Phi_M^a = \Phi_M^{a,a}$, and all the superscripts are omitted when $a = 0$.

Thanks to [7, Lemma 2.5], a standard calculation gives

$$D_{0+}^\theta S_k^{\beta-\theta,0} = \frac{\Gamma(k+1)}{\Gamma(k+1-\theta)} t^{-\theta} S_k^{\beta,-\theta}(t), \quad (82)$$

$$D_{T-}^\theta S_k^{0,\beta-\theta} = \frac{\Gamma(k+1)}{\Gamma(k+1-\theta)} (T-t)^{-\theta} S_k^{-\theta,\beta}(t), \quad (83)$$

where $0 < \theta < 1$ and $-1 < \beta < \infty$.

Lemma A.1 *For any $v \in H^{\alpha/2}(0, T)$, it holds that*

$$\left\langle D_{0+}^\alpha (I - \Phi_M^{-\alpha,0})v, q \right\rangle_{H^{\alpha/2}(0,T)} = 0 \quad \forall q \in P_M(0, T). \quad (84)$$

Consequently, we have the stability:

$$\left| \Phi_M^{-\alpha,0} v \right|_{H^{\alpha/2}(0,T)} \leq C_\alpha |v|_{H^{\alpha/2}(0,T)}, \quad (85)$$

and the convergence: $\lim_{M \rightarrow \infty} |(I - \Phi_M^{-\alpha,0})v|_{H^{\alpha/2}(0,T)} = 0$.

Proof Given any fixed $v \in H^{\alpha/2}(0, T)$, by [17, Theorem 1.4.4.3], we know that $v \in L^2_{\mu^{-\alpha,0}}(0, T)$. To prove (84), it is enough to consider $q = S_k^{0,-\alpha}$ for any $0 \leq k \leq M$. Thanks to (83), we have

$$D_{T-}^\alpha q = \frac{\Gamma(k+1)}{\Gamma(k+1-\alpha)} (T-t)^{-\alpha} S_k^{-\alpha,0}.$$

Again, it follows from [17, Theorem 1.4.4.3] that $D_{T-}^\alpha q \in (H^{\alpha/2}(0, T))^*$. Thus using the definition of $\Phi_M^{-\alpha,0}$ and Lemma 2.1 gives

$$\begin{aligned} \left\langle D_{0+}^\alpha (I - \Phi_M^{-\alpha,0})v, q \right\rangle_{H^{\alpha/2}(0,T)} &= \left\langle (I - \Phi_M^{-\alpha,0})v, D_{T-}^\alpha q \right\rangle_{(H^{\alpha/2}(0,T), (H^{\alpha/2}(0,T))^*)} \\ &= \frac{\Gamma(k+1)}{\Gamma(k+1-\alpha)} \left\langle (I - \Phi_M^{-\alpha,0})v, (T-t)^{-\alpha} S_k^{-\alpha,0} \right\rangle_{(0,T)} \\ &= 0. \end{aligned}$$

This establishes (84) and by Lemma 2.1, we have

$$\begin{aligned} \cos(\alpha\pi/2) \left| \Phi_M^{-\alpha,0} v \right|_{H^{\alpha/2}(0,T)}^2 &= \left\langle D_{0+}^\alpha \Phi_M^{-\alpha,0} v, \Phi_M^{-\alpha,0} v \right\rangle_{H^{\alpha/2}(0,T)} \\ &= \left\langle D_{0+}^\alpha v, \Phi_M^{-\alpha,0} v \right\rangle_{H^{\alpha/2}(0,T)} \\ &\leq \left| \Phi_M^{-\alpha,0} v \right|_{H^{\alpha/2}(0,T)} |v|_{H^{\alpha/2}(0,T)}, \end{aligned}$$

which implies (85).

By (84) and the proof of (85), we find that

$$|(I - \Phi_M^{-\alpha,0})v|_{H^{\alpha/2}(0,T)} \leq \sec(\alpha\pi/2) |v - q|_{H^{\alpha/2}(0,T)} \quad \forall q \in P_M(0, T).$$

Therefore, a standard density argument leads to

$$\lim_{M \rightarrow \infty} |(I - \Phi_M^{-\alpha, 0})v|_{H^{\alpha/2}(0, T)} = 0.$$

This finishes the proof of this lemma. \square

B Proof of the Commutativity (57)

Let $\{x_i\}_{i \in \mathbb{N}}$ and $\{y_j\}_{j \in \mathbb{N}}$ be the orthonormal basis of X and Y , respectively. Assume $Ax_i = \sum_{j=0}^{\infty} a_{ij} y_j$ with $a_{ij} \in \mathbb{R}$ for all $i \in \mathbb{N}$. It is clear that

$$\sum_{j=0}^{\infty} |a_{ij}|^2 = \|Ax_i\|_Y^2 \leq \|A\|_{X \rightarrow Y}^2 \|x_i\|_X^2 \quad \text{for all } i \in \mathbb{N}, \quad (86)$$

where $\|A\|_{X \rightarrow Y}$ denotes the operator norm of A .

We claim first that by definition, $\Phi_{M, Z}^{a, b} v_n \xrightarrow{n \rightarrow \infty} \Phi_{M, Z}^{a, b} v$ in $L_{\mu^{a, b}}^2(0, T; Z)$ whenever $v_n \xrightarrow{n \rightarrow \infty} v$ in $L_{\mu^{a, b}}^2(0, T; Z)$ for $Z = X$ or Y . Besides, we have the identity

$$\begin{aligned} \|w\|_{L_{\mu^{a, b}}^2(0, T; Z)}^2 &= \sum_{i=0}^{\infty} \|w_i\|_{L_{\mu^{a, b}}^2(0, T)}^2 = \int_0^T \sum_{i=0}^{\infty} |w_i(t)|^2 \mu^{a, b}(t) dt \\ &= \int_0^T \|w(t)\|_Z^2 \mu^{a, b}(t) dt, \end{aligned}$$

for all $w = \sum_{i=0}^{\infty} w_i z_i \in L_{\mu^{a, b}}^2(0, T; Z)$, where $z_i = x_i$ or y_i and we used the monotone convergence theorem (see [6, Theorem 4.1, pp.90]). Based on this, let us verify $Av_n \rightarrow Av$ in $L_{\mu^{a, b}}^2(0, T; Y)$ provided that $v_n \xrightarrow{n \rightarrow \infty} v$ in $L_{\mu^{a, b}}^2(0, T; X)$. Indeed,

$$\begin{aligned} \|Av_n - Av\|_{L_{\mu^{a, b}}^2(0, T; Y)}^2 &= \int_0^T \|(Av_n - Av)(t)\|_Y^2 \mu^{a, b}(t) dt \\ &\leq \|A\|_{X \rightarrow Y}^2 \int_0^T \|(v_n - v)(t)\|_X^2 \mu^{a, b}(t) dt \\ &= \|A\|_{X \rightarrow Y}^2 \|v - v_n\|_{L_{\mu^{a, b}}^2(0, T; X)}^2. \end{aligned}$$

Now, we take $v_n = \sum_{i=0}^n v_i x_i$, which converges to v in $L_{\mu^{a, b}}^2(0, T; X)$. According to the above discussions, $\Phi_{M, X}^{a, b} v_n \xrightarrow{n \rightarrow \infty} \Phi_{M, X}^{a, b} v$ in $L_{\mu^{a, b}}^2(0, T; X)$ and $Av_n \xrightarrow{n \rightarrow \infty} Av$ in $L_{\mu^{a, b}}^2(0, T; Y)$. To prove (57), it is sufficient to establish

$$A\Phi_{M, X}^{a, b} v_n = \Phi_{M, Y}^{a, b} Av_n. \quad (87)$$

Consider $\xi_i^m = \sum_{j=0}^m a_{ij} y_j$, which converges to Ax_i by (86) and further implies that

$$\sum_{i=0}^n \xi_i^m \Phi_M^{a, b} v_i \xrightarrow{m \rightarrow \infty} \sum_{i=0}^n Ax_i \Phi_M^{a, b} v_i = A\Phi_{M, X}^{a, b} v_n \quad \text{in } L_{\mu^{a, b}}^2(0, T; Y). \quad (88)$$

On the other hand, we find

$$\sum_{i=0}^n \xi_i^m \Phi_M^{a,b} v_i = \sum_{j=0}^m \left(\sum_{i=0}^n a_{ij} \Phi_M^{a,b} v_i \right) y_j = \Phi_{M,Y}^{a,b} \sum_{j=0}^m \left(\sum_{i=0}^n a_{ij} v_i \right) y_j = \Phi_{M,Y}^{a,b} \sum_{i=0}^n v_i \xi_i^m.$$

Since

$$\sum_{i=0}^n v_i \xi_i^m \xrightarrow{m \rightarrow \infty} \sum_{i=0}^n v_i A x_i = A v_n \quad \text{in } L_{\mu^{a,b}}^2(0, T; Y),$$

we conclude that

$$\sum_{i=0}^n \xi_i^m \Phi_M^{a,b} v_i \xrightarrow{m \rightarrow \infty} \Phi_{M,Y}^{a,b} A v_n \quad \text{in } L_{\mu^{a,b}}^2(0, T; Y).$$

This together with (88) proves (87) and completes the proof.

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